Stochastic nonlinear PDEs with singular drift

and gradient noise

Jonas Tölle

乔涛

"Qiáo Tāo"

(Universität Augsburg)

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Motivation

- The p-Laplace equation

The *p*-Laplace equation

The *p*-Laplace evolution equation

$$\partial_t u = \operatorname{div}(|\nabla u|^{p-2}\nabla u) + f$$

is called

- degenerate for 2 ,
- singular for 1 ,
- it reduces to the *heat equation* for p = 2,
- the borderline case p = 1 is called *total variation (TV-) flow*.

Aim: Replace the force f with noise input $G(\cdot, u, \nabla u) \partial_t W(t, \cdot)$.

The p-Laplace equation

Incompressible non-Newtonian fluid dynamics.

For $v(\cdot) \in \mathbb{R}^3$, the *p*-Laplace type *diffusivity* can be found in

$$\begin{cases} \operatorname{div} v = 0\\ \partial_t v + \operatorname{div}(v \otimes v) - \nu \operatorname{div}(|Dv|^{p-2}Dv) &= -\nabla \pi + b \end{cases}$$

the equations for the velocity-field of a power-law fluid.

p > 2

Dilatant, or shear-thickening. Examples: ooze / oobleck (mixture of water and corn-starch).



р < 2

Pseudoplastic, or *shear-thinning*. Examples: hair-gel (polymeric molecules).



p = 2

Situation of Newtonian fluids — Navier-Stokes equations. Examples: water, glycerol, ethanol.



Stochastic nonlinear PDEs with singular drift and gradient noise

- Motivation

The p-Laplace equation

Stochastic singular p-Laplace equation

Well-posedness for the stochastic scalar singular p-Laplace evolution equation

(with additive Gaussian noise)

$$du = \operatorname{div}(|\nabla u|^{p-2}\nabla u) \, dt + dW$$

on a bounded domain $\mathcal{O} \subset \mathbb{R}^d$ for the case $\left(1 \lor \frac{2d}{d+2}\right) was first studied in$

[Liu, W., J. Math. Anal. Appl. (2009)]

in a similar variational setup as in

[Zhang, X., Stochastics and Dynamics (2009)],

[Ren, J./Röckner, M./Wang, F.-Y., J. Differential Equations (2007)],

extending [Krylov, N.V./Rozovskii, B.L. (1979)].

For stochastically forced vector-valued case, see e.g.: [Breit, D., J. Math. Fluid Mech. (2015)].

- Motivation

The p-Laplace equation

Stochastic singular p-Laplace equation

Further well-posedness results for multiplicative noise (not depending on ∇u)

$$du = \operatorname{div}(|\nabla u|^{p-2}\nabla u) \, dt + \mathbf{B}(u) \, dW, \quad u(0) = u_0,$$

were obtained in:

- [Barbu, V./Röckner, M., Arch. Ration. Mech. Anal. (2013)] for p = 1 (TV-flow)
- Gess, B./T, J. Math. Pures Appl. (2014)] for $p \in [1, 2]$, for initial data $u_0 \in H^1(\mathcal{O})$
- [Barbu, V./Röckner, M., J. Eur. Math. Soc. (2015)] general method for linear multiplicative noise
- [Gess, B./T, J. Differential Equations (2016)] for $p \in [1, 2]$, for initial data $u_0 \in L^2(\mathcal{O})$ and for **nonlocal** *p*-Laplace; **robustness** of the solutions for $p \to 1$
- [Gess, B./Röckner, M., Trans. Amer. Math. Soc. (2017)], higher regularity and more general noise
- [Marinelli, C./Scarpa, L., SPDE: Anal. Comp. (2018)], more general growth conditions

Stochastic nonlinear PDEs with singular drift and gradient noise

- Motivation

The p-Laplace equation

Stratonovich noise *p*-Laplace

On the *d*-dimensional flat torus $\mathbb{T}^d := \mathbb{R}^d / \mathbb{Z}^d$, consider:

$$dX_t = \operatorname{div}(a^*\phi(a\nabla X_t)) dt + \langle b\nabla X_t, \circ d\beta_t \rangle, \quad X_0 = x \in L^2(\mathbb{T}^d).$$
(SPDE)

(SPDE) reduces to stochastic *p*-Laplace with multiplicative Stratonovich gradient noise/transport noise for a = 1 and for

$$\phi(z) = |z|^{p-2}z, \quad z \in \mathbb{R}^d, \ p \in (1,\infty).$$

Note.

Here, we shall consider the case of any $d \in \mathbb{N}$ and any $p \in [1, 2]$.

 \longrightarrow We do not need Sobolev embeddings.

Motivation

The p-Laplace equation

Stratonovich noise *p*-Laplace

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with:

1 a monotone nonlinearity $\phi : \mathbb{R}^d \to \mathbb{R}^d$ or (multi-valued) $\phi : \mathbb{R}^d \to 2^{\mathbb{R}^d}$ of (at most) linear growth (corresponds to $p \leq 2$),

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- 2 C¹-coefficient fields $a, b : \mathbb{T}^d \to \mathbb{R}^{d \times d}$,

- Motivation

└─ The *p*-Laplace equation

Stratonovich noise *p*-Laplace

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- 2 C^1 -coefficient fields $a, b : \mathbb{T}^d \to \mathbb{R}^{d \times d}$,
- 3 a *d*-dimensional Wiener process t → β_t = (β¹_t,...,β^d_t) on a filtered standard probability space (Ω, F, (F_t)_{t≥0}, ℙ).

(Evolution) variational inequalities — general idea

(Evolution) variational inequalities — general idea

Suppose that the nonlinear operator

$$A(u) := \operatorname{div}(a^*\phi(a\nabla u)), \quad u \in \operatorname{dom}(A),$$

is the negative Gâteaux gradient

$$-D\Psi(\cdot): \operatorname{dom}(D\Psi) \subset L^2(\mathbb{T}^d) \to L^2(\mathbb{T}^d)^*$$

for some (convex) potential $\Psi : L^2(\mathbb{T}^d) \to \mathbb{R}$.

We will see soon, that this is the case.

Assume first that $b \equiv 0$. Then (SPDE) is has a gradient flow structure in L^2 ,

$$\dot{u} = -D\Psi(u), \quad u \in L^2.$$

Gradient noise SPDE (in a variational setting)

(Evolution) variational inequalities — general idea

Evolution variational inequalities

Starting from a solution $[0, T] \ni t \mapsto u(t)$ to

$$\dot{u} = -D\Psi(u), \quad u \in L^2,$$

such that u(0) = x,

 $du = -D\Psi(u) dt$

Gradient noise SPDE (in a variational setting)

(Evolution) variational inequalities — general idea

Evolution variational inequalities

Starting from a solution $[0, T] \ni t \mapsto u(t)$ to

$$\dot{u} = -D\Psi(u), \quad u \in L^2,$$

such that u(0) = x, we may write for $z \in C^1([0, T], L^2)$,

$$d(u-z) = -D\Psi(u)\,dt - \dot{z}\,dt.$$

(Evolution) variational inequalities — general idea

Evolution variational inequalities

Starting from a solution $[0, T] \ni t \mapsto u(t)$ to

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$$d(u-z) = -D\Psi(u)\,dt - \dot{z}\,dt.$$

Applying the change of variable formula for $\|\cdot\|_{L^2}^2$ (where $D\|u\|_{L^2}^2 = 2(u, \cdot)_{L^2}$), we get for $t \in [0, T]$,

$$\|u(t)-z(t)\|_{L^{2}}^{2}-\|x-z(0)\|_{L^{2}}^{2}=2\int_{0}^{t}(D\Psi(u(s))+\dot{z}(s),z(s)-u(s))_{L^{2}}\,ds.$$

— (Evolution) variational inequalities — general idea

Evolution variational inequalities

Recall that Ψ was assumed convex and hence $D\Psi$ satisfies (in fact, is characterized by) its *subpotential property*

$$(D\Psi(u), z-u)_{L^2} \leqslant \Psi(z) - \Psi(u) \quad \forall z \in L^2.$$

Then

$$\|u(t) - z(t)\|_{L^2}^2 - \|x - z(0)\|_{L^2}^2 = 2\int_0^t (D\Psi(u(s)) + \dot{z}(s), z(s) - u(s))_{L^2} ds$$

leads to

$$\|u(t) - z(t)\|_{L^{2}}^{2} + 2\int_{0}^{t} \Psi(u(s)) ds$$

$$\leq \|x - z(0)\|_{L^{2}}^{2} + 2\int_{0}^{t} \Psi(z(s)) ds + 2\int_{0}^{t} (\dot{z}(s), z(s) - u(s))_{L^{2}} ds$$
(EVI)

Gradient noise SPDE (in a variational setting)

(Evolution) variational inequalities — general idea

Evolution variational inequalities (EVI)

Definition

Let $x \in L^2$. A continuous path $u \in C([0, T], L^2)$ is called *EVI-solution* to

$$\dot{u} = -D\Psi(u), \quad u(0) = x,$$

if

$$\Psi(u(\cdot)) \in L^1([0,T]) \tag{REG}$$

and if for every $t \in [0, T]$ and for every $z \in C^1([0, T], L^2)$ it holds that

$$\|u(t) - z(t)\|_{L^{2}}^{2} + 2\int_{0}^{t} \Psi(u(s)) ds$$

$$\leq \|x - z(0)\|_{L^{2}}^{2} + 2\int_{0}^{t} \Psi(z(s)) ds + 2\int_{0}^{t} (\dot{z}(s), z(s) - u(s))_{L^{2}} ds.$$
(EVI)

Some remarks

- We can dispense with the requirement that $u(\cdot) \in \text{dom}(D\Psi)$ for which usually $\text{dom}(D\Psi) \subsetneq L^2$ holds.
- The right hand side of (EVI) can be equal to $+\infty$.
- Strong solutions are automatically EVI-solutions, as seen above.
- For sufficiently regular Ψ , EVI-solutions are also strong solutions.

In many cases, and also in our case, dom $(\Psi) \stackrel{\subseteq}{\neq} L^2$. We overcome this by setting $\Psi \equiv +\infty$ on $L^2 \setminus \text{dom}(\Psi)$.

One would also like to have that the new potential $\Psi : L^2 \to \mathbb{R} \cup \{+\infty\}$ is lower semi-continuous (l.s.c.) in L^2 .

In the convex situation, one can usually take the l.s.c. envelope for this purpose.

— (Evolution) variational inequalities — general idea

The gradient structure of $A = \operatorname{div}(a^*\phi(a\nabla \cdot))$

Let $\phi = \partial \psi$, where $\psi : \mathbb{R}^d \to [0, \infty)$.

(For convex $\psi : \mathbb{R}^d \to \mathbb{R}$: $\eta \in \partial \psi(\zeta)$ iff $\langle \eta, w - \zeta \rangle \leq \psi(w) - \psi(\zeta)$ for every $w \in \mathbb{R}^d$.)

Set

$$\widetilde{\Psi}: u \mapsto \int_{\mathbb{T}^d} \psi(a \nabla u) \, d\xi$$

Then consider its l.s.c. envelope

$$\Psi := \inf \left\{ \liminf_{n \to \infty} \widetilde{\Psi}(u_n) \mid u_n \to u \in L^2(\mathbb{T}^d) \text{ strongly} \right\}.$$

(Evolution) variational inequalities — general idea

The gradient structure of $A = \operatorname{div}(a^*\phi(a\nabla \cdot))$

On a formal level, we have that

$$A = (a\nabla)^* \circ \partial \Psi \circ (a\nabla),$$

however, we may avoid

- the characterization of the domain of A or the domain of Ψ ,
- singular energy spaces on weighted Riemannian manifolds of the type $W^{1,p}(\mathbb{T}^d, g_a, d\xi), p \approx 1$, or $BV(\mathbb{T}^d, g_a, d\xi)$ where $g_a = (a^*a)^{-1}$,
- **non**-Hilbertian Gelfand triples $V \subset H \subset V^*$,

by employing stochastic variational inequalities (SVI).

About the drift part

 a monotone (multi-valued) nonlinearity φ : ℝ^d → ℝ^d or φ : ℝ^d → 2^{ℝ^d} of at most linear growth.

Singular case

We assume that there exist $C \ge 0$, K > 0, such that

- $\phi = \partial \psi$, where $\psi : \mathbb{R}^d \to [0, \infty)$ and $\psi(\zeta) = \rho(|\zeta|)$ for all $\zeta \in \mathbb{R}^d$,
 - where $\rho : [0, \infty) \to [0, \infty)$, convex, continuous,
 - $\rho(0) = 0$, $\lim_{r \to \infty} \rho(r) = \infty$,
 - $\rho(r) \leq C(1+|r|^2)$, for every $r \geq 0$, (quadratic growth condition)
 - $\rho(2r) \leq K\rho(r)$, for every $r \geq 0$ (doubling, or Δ_2 -condition)

Example

Example

For $\phi = \partial \psi$, the following examples satisfy the previous conditions for $a \equiv 1$:

•
$$\psi(\zeta) := rac{1}{p} |\zeta|^p$$
, $p \in [1, 2]$, $\zeta \in \mathbb{R}^d$,

leading to the *p*-Laplace drift term div $[|\nabla \cdot |^{p-2}\nabla \cdot]$,

•
$$\psi(\zeta) := (1 + |\zeta|) \log(1 + |\zeta|) - |\zeta|, \ \zeta \in \mathbb{R}^d,$$

■ leading to a special type of *logarithmic diffusion* drift term div[log(1 + |∇ · |) sgn(∇·)].

Ellipticity

- 1 a monotone (multi-valued) nonlinearity $\phi : \mathbb{R}^d \to \mathbb{R}^d$ or $\phi : \mathbb{R}^d \to 2^{\mathbb{R}^d}$ of at most linear growth.
- 2 C^1 -coefficient fields $a, b : \mathbb{T}^d \to \mathbb{R}^{d \times d}$.

Assume the following *uniform ellipticity condition*: $\exists \kappa > 0$:

$$|a(\xi)\zeta|^2 \ge \kappa |\zeta|^2$$
 for all $\zeta \in \mathbb{R}^d$ and all $\xi \in \mathbb{T}^d$.

For simplicity, assume a similar condition for *b*.

Note.

We do neither assume that div $a_i = 0$ nor that div $b_i = 0$, where a_i , b_i denote the rows of a, b respectively. As a consequence, the noise coefficient operator is not skew-symmetric. (\longrightarrow BDG-inequality **not** applicable **in our proof**).

Stratonovich ~> Itô

Fix a *d*-dimensional Wiener process $t \mapsto \beta_t = (\beta_t^1, \dots, \beta_t^d)$ on a filtered standard probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \ge 0}, \mathbb{P})$.

Instead of the Stratonovich SPDE with linear degenerate gradient/transport noise

$$dX_t = \operatorname{div}(a^*\phi(a\nabla X_t)) dt + \langle b\nabla X_t, \circ d\beta_t \rangle, \quad X_0 = x \in L^2(\mathbb{T}^d)$$

we actually consider the Itô SPDE (recall the formula $f(X) \circ dX = f(X) dX + \frac{1}{2}d[f(X), X]$)

$$dX_t = \operatorname{div}(a^*\phi(a\nabla X_t)) dt + \frac{1}{2}L^b X_t dt + \langle b\nabla X_t, d\beta_t \rangle, \quad X_0 = x \in L^2(\mathbb{T}^d),$$

where L^b denotes the generator of the Dirichlet form

$$\mathcal{B}(u, v) := \int_{\mathbb{T}^d} \langle b \nabla u, b \nabla v \rangle \, d\xi$$

On a core of smooth functions: $L^b u = \operatorname{div}(b^* b \nabla u)$, $u \in C^{\infty}(\mathbb{T}^d)$. See e.g. [Friz, P.K./Hairer, M., Ch. 12, Springer (2014)] for more general transport noise with other nonlinear drift terms.

The (geometric) structure of the equation

Curvature dimension conditions

A weighted Riemannian manifold

Set $g_a := (a^*a)^{-1}$. Then \mathbb{T}^d , with the Lebesgue measure $d\xi$, is a weighted Riemannian manifold with metric g_a and with density $\rho_a := \sqrt{\det(a^*a)}$ w.r.t. the Riemannian volume.

Let $L^a u = \operatorname{div}(a^* a \nabla u)$ be the Dirichlet operator associated to the Dirichlet form

$$\mathcal{A}(u,v) := \int_{\mathbb{T}^d} \langle a \nabla u, a \nabla v \rangle \, d\xi.$$

Then $L^a = \Delta^a$ is the Laplace-Beltrami operator on $(\mathbb{T}^d, g_a, d\xi)$.

- The (geometric) structure of the equation
 - Curvature dimension conditions

Curvature-dimension condition

Definition

Let $\Lambda^a := \{f \in H^1(\mathbb{T}^d) : L^a f \in H^1(\mathbb{T}^d)\}$. We say that $(\mathbb{T}^d, g_a, d\xi)$ satisfies a *Bakry-Émery curvature-dimension condition* $BE(K, \infty)$ if there exists $K \in \mathbb{R}$ such that

$$L^{a}|a\nabla f|^{2}-2\langle a\nabla f,a\nabla L^{a}f\rangle \geqslant rac{K}{2}|a\nabla f|^{2} \quad \forall f\in\Lambda^{a}.$$

Let $(P_t^a)_{t \ge 0}$ be the heat semigroup associated to \mathcal{A} .

Theorem (cf. [Wang, F.-Y., Bull. Sci. Math. (2011)])

 $BE(K,\infty)$ is equivalent to

 $|a\nabla P_t^a f| \leqslant e^{-2\kappa t} P_t^a |a\nabla f| \quad \forall t \ge 0 \; \forall f \in C^1(\mathbb{T}^d).$

— The (geometric) structure of the equation

Defective commutation condition

Defective commutation condition

Definition

Let $R: H^1(\mathbb{T}^d) \to L^2(\mathbb{T}^d; \mathbb{R}^d)$ be a bounded linear operator such that there exists C > 0 with

$$\|Ru\|^2_{L^2(\mathbb{T}^d;\mathbb{R}^d)} \leqslant C\mathcal{A}(u,u) \quad \forall u \in H^1(\mathbb{T}^d).$$

We say that the *weak defective commutation property* holds for the operators $u \mapsto b\nabla u$ and L^a if there exists an operator R with the above properties such that for every $\beta > 0$,

$$b \nabla G^a_{\beta} u = G^a_{\beta} b \nabla u + G^a_{\beta} R G^a_{\beta} u \quad \forall u \in H^1(\mathbb{T}^d),$$

where $G^a_{\beta} := (\beta - L^a)^{-1}$, $\beta > 0$ denotes the *resolvent* of L^a .

— The (geometric) structure of the equation

Defective commutation condition

The weak defective commuation property e.g. holds if

 $b\nabla L^a = L^a b\nabla + R$

holds on some core of L^a, see [Shigekawa, I., *J. Funct. Anal.* (2006)]. This can be viewed a kind of *stochastic parabolicity condition*.

Compare also with the *Weitzenböck formula* $\Box^a = \Delta^a + R$, where

 $\square^a := -(dd^* + d^*d)$ is the Hodge-de Rham Laplace, and R is the curvature tensor.

Lemma

The weak defective commutation condition implies that there exists a constant $c \in \mathbb{R}$ such that for every $\beta > 0$, we have that

$$\beta \int_{\mathbb{T}^d} \langle \beta G^a_\beta b \nabla f - \beta b \nabla G^a_\beta f, b \nabla f \rangle \, d\xi \ge c \mathcal{A}(f, f) \quad \forall f \in H^1(\mathbb{T}^d). \tag{R}$$

Recall that $\beta(\beta G^a_{\beta}u - u) \rightarrow L^a u$ as $\beta \rightarrow \infty$ for $u \in D(L^a)$.

— The (geometric) structure of the equation

Defective commutation conditior

Example: rigid motions

By [Sumitomo, *Hokkaido Math. J.* (1972)], it is necessary and sufficient for the first order operators $B_i := \langle b_i, \nabla \cdot \rangle$ (where b_i are the rows of b) to commute with the Laplace-Beltrami operator L^b on a core of *smooth functions* that

b_i is a Killing vector field,

meaning that, the Jakobian of b_i is skew-symmetric, i.e.

$$\partial_j b_i^k + \partial_k b_i^j = 0 \quad \forall 1 \leq j, k \leq d.$$

This automatically implies that div $b_i = 0$. These vector fields generate the group of direct affine isometries or rigid motions, that is, the Lie group SE(d).

In this particular case, by [Shigekawa, I., *Acta Appl. Math.* (2000)], we get the weak (defective) commutation, whenever a = b.

- Well-posedness

Approximative estimate

Approximation of the equation

Consider solutions $X = X^{n,\lambda,\delta,\varepsilon,m}$ to

$$dX_{t} = \left[\operatorname{div}(a^{*}\phi^{\lambda}(a\nabla X_{t})) + \varepsilon L^{a}X_{t} + \frac{1}{2}J_{\delta}^{a}L^{b}J_{\delta}^{a}X_{t} \right] dt + \sum_{i=1}^{d} \langle b_{i}, \nabla J_{\delta}^{a}(\eta_{m} * X_{t}) \rangle d\beta_{t}^{i},$$

$$X_{0} = x_{n} \in H^{1}(\mathbb{T}^{d}),$$

where $\varepsilon > 0$ and

- $J^a_{\delta} := (1 \delta L^a)^{-1} = \delta^{-1} G^a_{1/\delta}, \ \delta > 0$, denotes the resolvent of the Laplace operator,
- ϕ^{λ} , $\lambda > 0$, denotes the Yosida approximation of ϕ ,
- $b = (b_1, \ldots, b_d)^*$,
- $(\eta_m)_{m \in \mathbb{N}}$ denotes a standard mollifier on \mathbb{T}^d .

- Well-posedness

Approximative estimate

Lemma (Limit solutions)

For $m \to \infty$, $x \in L^2(\Omega, \mathcal{F}_0, \mathbb{P}; L^2(\mathbb{T}^d))$ there exists a unique limit solution^{*} with continuous paths, denoted by $X = X^{n,\lambda,\delta,\varepsilon}$, to the approximating equation

$$dX_{t} = \left[\operatorname{div}(a^{*}\phi^{\lambda}(a\nabla X_{t})) + \varepsilon L^{a}X_{t} + \frac{1}{2}J_{\delta}^{a}L^{b}J_{\delta}^{a}X_{t} \right] dt + \sum_{i=1}^{d} \langle b_{i}, \nabla J_{\delta}^{a}(X_{t}) \rangle d\beta_{t}^{i},$$

$$X_{0} = x_{n} \in H^{1}(\mathbb{T}^{d}).$$

Proof.

Fixed-point and perturbation argument, see [Gess, B./T, JMPA (2014)].

*i..e., $\mathbb{E}\left[\sup_{t\in[0,T]} \|X_t^{m,x_m} - X_t^x\|_{L^2}^2\right] \to 0$ as $m \to \infty$ for every sequence of initial conditions with $x_m \in H^1$ such that $\mathbb{E}\|x_m - x\|^2 \to 0$ and for every sequence of noise coefficients $\|B^m - B\|_{L^2(\mathbb{R}^d, L^2)} \to 0$.

- Well-posedness

Approximative estimate

Two a priori estimates

Proposition ([T, SPDERF, in honor of Michael Röckner, Springer (2018)])

Under the above geometric conditions, $X = X^{n,\lambda,\delta,\varepsilon}$ satisfies the following two energy bounds:

$$\operatorname{ess\,sup}_{t\in[0,T]} \left[\mathbb{E}\|X_t\|_{L^2}^2\right] + 2\mathbb{E}\int_0^T \int_{\mathbb{T}^d} \psi^{\lambda}(a\nabla J_{\delta}X_t) \, d\xi \, dt + 2\varepsilon \mathbb{E}\int_0^T \mathcal{A}(X_t, X_t) \, dt \leqslant \mathbb{E}\|x_n\|_{L^2}^2.$$

$$\operatorname{ess sup}_{t\in[0,T]} \left[\mathbb{E}\mathcal{A}(X_t, X_t)\right] + 2\varepsilon \mathbb{E} \int_0^T \left\|L^a X_t\right\|_{L^2}^2 dt \leqslant e^{-CT} \mathcal{A}(x_n, x_n).$$

The second estimate changes slightly if $K \leq 0$ or $c \leq 0$ in the curvature-dimension condition on a or condition (R) for b respectively.

Stochastic nonlinear PDEs with singular drift and gradient noise

- Well-posedness

Approximative estimate

Stochastic variational inequality (SVI)

Denote $H = L^2(\mathbb{T}^d)$, $S = H^1(\mathbb{T}^d)$. Let $U := \mathbb{R}^N$. Denote by $L_2(U, H)$ the space of linear Hilbert-Schmidt operators from U to H.

Denote $B(x)\zeta := \sum_{i=1}^{N} \langle b_i, \nabla x \rangle \zeta^i$. Denote by Ψ the l.s.c. envelope of

$$u \mapsto \begin{cases} \int_{\mathbb{T}^d} \psi(a\nabla u) \, d\xi, & u \in H^1(\mathbb{T}^d), \\ +\infty, & u \in L^2(\mathbb{T}^d) \setminus H^1(\mathbb{T}^d) \end{cases}$$

Definition

Let $x \in L^2(\Omega, \mathcal{F}_0, \mathbb{P}; H)$, T > 0. A progressively measurable map $X \in L^2([0, T] \times \Omega; H)$ is said to be an *SVI-solution* to (SPDE) if there exists a constant C > 0 such that

(Regularity) $\operatorname{ess\,sup}_{t \in [0,T]} \mathbb{E} \|X_t\|_{H}^{2} + 2\mathbb{E} \int_{0}^{T} \Psi(X_s) \, ds \leqslant \mathbb{E} \|x\|_{H}^{2}.$

Stochastic nonlinear PDEs with singular drift and gradient noise

- Well-posedness

Approximative estimate

Definition (*cont'd*)

• (Variational inequality) For every admissible test-function $Z \in L^2([0, T] \times \Omega; D(L^b))$, that is, there are $Z_0 \in L^2(\Omega, \mathcal{F}_0, \mathbb{P}; S)$, $G \in L^2([0, T] \times \Omega; H)$, $P \in L(H)$ such that G is progressively measurable, such that $P(D(L^b)) \subset D(L^b)$ and such that

$$Z_t = Z_0 + \int_0^t G_s \, ds + \frac{1}{2} \int_0^t P^* L^b P Z_s \, ds + \int_0^t B P Z_s \, d\beta_s \quad \forall t \in [0, T],$$

we have that

$$\mathbb{E} \|X_t - Z_t\|_{H}^{2} + 2\mathbb{E} \int_0^t \Psi(X_s) \, ds$$

$$\leq \mathbb{E} \|x - Z_0\|_{H}^{2} + 2\mathbb{E} \int_0^t \Psi(Z_s) \, ds$$

$$- 2\mathbb{E} \int_0^t (G_s, X_s - Z_s)_{H} \, ds$$

$$- \mathbb{E} \int_0^t (L^b P Z, P X - X)_{H} \, ds - \mathbb{E} \int_0^t (X, L^b (Z - P Z))_{H} \, ds$$

for almost all $t \in [0, T]$.

- Well-posedness
 - └─ The main result

The main result

Theorem (T, (2018+) https://arxiv.org/abs/1803.07005)

Suppose that the conditions from the beginning hold for ψ . Suppose that a, b are bounded and uniformly elliptic. Suppose that the curvature-dimension condition holds for a. Suppose that the weak defective commutation property holds for $b\nabla$ and L^{a} .[†]

Then there exists a unique adapted time-continuous SVI-solution $X \in C([0, T]; L^2(\Omega; L^2(\mathbb{T}^d)))$ to (SPDE) for every initial datum $x \in L^2(\Omega, \mathcal{F}_0, \mathbb{P}; L^2(\mathbb{T}^d))$ for every finite time-horizon T > 0such that

$$\operatorname{ess\,sup}_{t\in[0,T]} \mathbb{E}\|X_t - Y_t\|_{L^2(\mathbb{T}^d)}^2 \leq \mathbb{E}\|x - y\|_{L^2(\mathbb{T}^d)}^2$$

for any other SVI-solution $Y \in C([0, T]; L^2(\Omega; L^2(\mathbb{T}^d)))$ starting in $y \in L^2(\Omega, \mathcal{F}_0, \mathbb{P}; L^2(\mathbb{T}^d))$.

[†]Assuming only condition (R) here is o.k., however, one then needs an additional technical condition on the domain of L^{b} .

- Well-posedness

Remarks on previous results

Remarks on previous results

Previously ... for nonlinear, singular drift (i.e. p < 2) and linear gradient/transport noise of the above type:

- Idea: Doss (1976), Sussmann (1978), Brzeźniak, Capiński, Flandoli (1988), ...
 - Stratonovich-to-Itô transformation, commuting noise coefficients.
- Tubaro (1988), Kunita (monograph 1990), ...
 - Method of stochastic characteristics.
- [Barbu, V./Brzeźniak, Z./Hausenblas, E./Tubaro, L., Stochastic Processes Appl. (2013)]:
 - Smooth bounded domain $\mathcal{O} \subset \mathbb{R}^d$, Dirichlet or Neumann boundary conditions,
 - In a Gelfand triple, e.g.: W^{1,p}(O) → L²(O) → W^{-1,q}(O), p > 1, p⁻¹ + q⁻¹ = 1. Method uses convex conjugates,
 - $\langle b_i, \nabla \cdot \rangle$ and $\langle b_j, \nabla \cdot \rangle$, $i \neq j$ generate C_0 -groups that are assumed to commute.

Stochastic nonlinear PDEs with singular drift and gradient noise ${\textstyle \bigsqcup_{\rm Well-posedness}}$

Remarks on previous results

■ [Ciotir, I./T, J. Funct. Anal. (2016)]:

Neumann boundary conditions on a convex bounded domain $\mathcal{O} \subset \mathbb{R}^d$,

- $b_i \in C^2$, $\partial O \in C^3$, commutation,
- **p = 1** total variation flow with gradient noise.
- [Munteanu, I./Röckner, M., Infin. Dimens. Anal. Quantum. Probab. Relat. Top. (2018)]:
 - Dirichlet boundary conditions on a bounded domain $\mathcal{O} \subset \mathbb{R}^d$,
 - $b_i \in C^2$, $\partial O \in C^3$, commutation,
 - **p** p = 1 total variation (TV-) flow with gradient noise.
 - Positivity and finite time extinction results.
- [Barbu, V./Brzeźniak, Z./Tubaro, L., Appl. Math. Optim. (2017)]:
 - L¹-theory under general assumptions (Brézis-Ekeland method convex conjugates),
 - **no uniqueness** for the TV-flow and weak continuity of paths.



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Thank you for your attention — 谢谢!