

Gradient flows for the stochastic Amari neural field model

Jonas M. Töle (Augsburg University)

joint work with

Christian Kuehn (TU Munich)

<https://arxiv.org/abs/1807.02575>

9th International Conference on Stochastic Analysis and its Applications

Bielefeld University

September 3, 2018



Contents

1 The stochastic Amari neural field model

- The model
- The stochastic PDE

2 A gradient flow formulation

- Change of ambient space
- Invariant measures
- Final remarks

Section 1

The stochastic Amari neural field model

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x,y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,
- $U : \mathcal{B} \times [0, T] \times \Omega \rightarrow \mathbb{R}$, "voltage"

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,
- $U : \mathcal{B} \times [0, T] \times \Omega \rightarrow \mathbb{R}$, "voltage"
- $\alpha > 0$, decay parameter, $0 < \varepsilon \ll 1$, noise intensity parameter,

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,
- $U : \mathcal{B} \times [0, T] \times \Omega \rightarrow \mathbb{R}$, "voltage"
- $\alpha > 0$, decay parameter, $0 < \varepsilon \ll 1$, noise intensity parameter,

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,
- $U : \mathcal{B} \times [0, T] \times \Omega \rightarrow \mathbb{R}$, “voltage”
- $\alpha > 0$, decay parameter, $0 < \varepsilon \ll 1$, noise intensity parameter,
- $w : \mathcal{B} \times \mathcal{B} \rightarrow \mathbb{R}$ kernel, modeling neural connectivity,

Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,
- $U : \mathcal{B} \times [0, T] \times \Omega \rightarrow \mathbb{R}$, "voltage"
- $\alpha > 0$, decay parameter, $0 < \varepsilon \ll 1$, noise intensity parameter,
- $w : \mathcal{B} \times \mathcal{B} \rightarrow \mathbb{R}$ kernel, modeling **neural connectivity**,
- $f : \mathbb{R} \rightarrow (0, +\infty)$ gain function, modeling **neural input**,

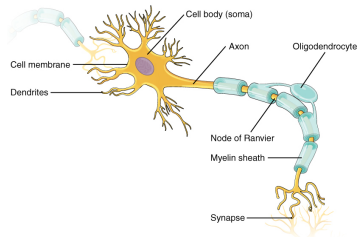
Stochastic PDE for mean-field cortex activity

Amari-type neural field model [Amari, *Biological Cybernetics* (1977)].

$$dU_t(x) = \left[-\alpha U_t(x) + \int_{\mathcal{B}} w(x, y) f(U_t(y)) dy \right] dt + \varepsilon B dW_t(x)$$

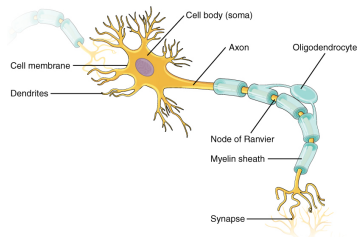
- $\mathcal{B} \subset \mathbb{R}^d$ bounded closed domain,
- $U : \mathcal{B} \times [0, T] \times \Omega \rightarrow \mathbb{R}$, “voltage”
- $\alpha > 0$, decay parameter, $0 < \varepsilon \ll 1$, noise intensity parameter,
- $w : \mathcal{B} \times \mathcal{B} \rightarrow \mathbb{R}$ kernel, modeling **neural connectivity**,
- $f : \mathbb{R} \rightarrow (0, +\infty)$ gain function, modeling **neural input**,
- $\{W_t\}_{t \geq 0}$ cylindrical Wiener process with values in $H := L^2(\mathcal{B})$, modeled on $(\Omega, \mathcal{F}, \mathbb{P})$; additive noise coefficient $B \in L(H)$.

Neuron

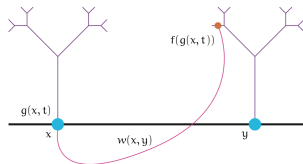


[OpenStax, Anatomy & Physiology (2018)]

Neuron / neural fields



[OpenStax, Anatomy & Physiology (2018)]



$g \sim$ voltage, $f \sim$ gain, $w \sim$ connectivity

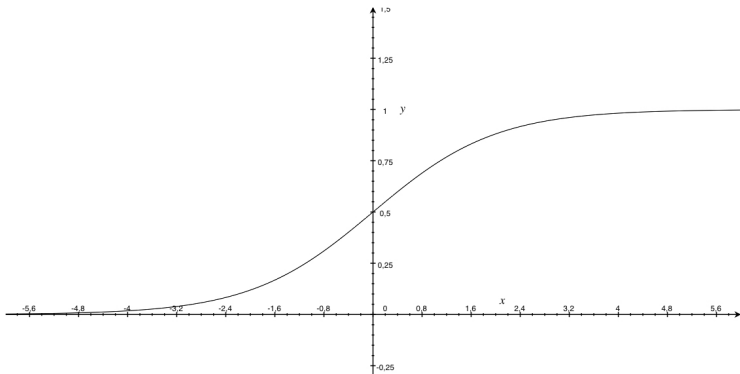
[Coombes, beim Graben, Potthast (2014)]

In: Neural Fields. Springer]

Typical gain functions f

Assume that $F : H \rightarrow H$, $F(v)(x) := f(v(x))$, $v \in H = L^2(\mathcal{B})$ is a **Nemytskii operator**.

$$f(s) = (1 + e^{-s})^{-1} \text{ (Sigmoid)}$$

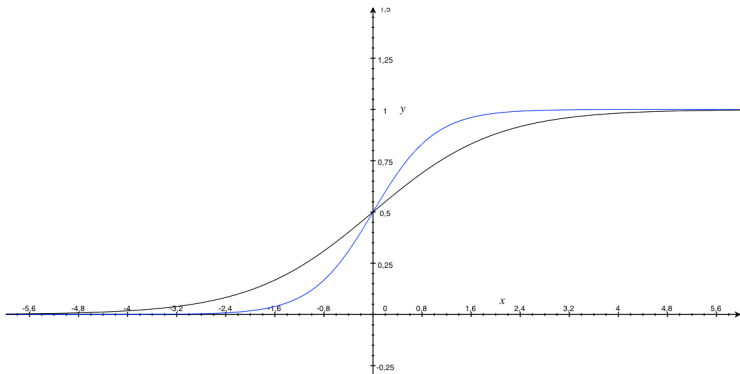


Typical gain functions f

Assume that $F : H \rightarrow H$, $F(v)(x) := f(v(x))$, $v \in H = L^2(\mathcal{B})$ is a **Nemytskii operator**.

$$f(s) = (1 + e^{-s})^{-1} \text{ (Sigmoid)}$$

$$f(s) = \frac{1}{2}(\tanh(s) + 1)$$



The kernel

Let $w : \mathcal{B} \times \mathcal{B} \rightarrow \mathbb{R}$ be measurable such that:

Assumption 1

- 1 $w(x, y) = w(y, x)$ for a.e. $x, y \in \mathcal{B}$,
- 2 $w \in L^2(\mathcal{B} \times \mathcal{B}) \cap C(\mathcal{B} \times \mathcal{B})$,
- 3 w satisfies

$$\sum_{i,j=1}^n c_i c_j w(x_i, x_j) \geq 0$$

for every $n \in \mathbb{N}$, for every $\{x_1, \dots, x_n\} \subset \mathcal{B}$, and for every $\{c_1, \dots, c_n\} \subset \mathbb{R}$.

$$w(x, y) = J(x - y)$$

Then Assumption 1 implies that the linear operator $K \in L(H)$ defined by

$$Kg(x) := \int_{\mathcal{B}} w(x, y)g(y) dy, \quad g \in H,$$

is a nonnegative definite, self-adjoint Hilbert-Schmidt operator and, moreover, even of trace-class (\longrightarrow **Mercer's theorem**), as w is a so-called **Mercer kernel** on a compact subset of \mathbb{R}^d .

Assumption 2

Let $J \in C(\mathbb{R}^d)$ such that $w(x, y) = J(x - y)$ for $x, y \in \mathcal{B}$.

Now, w satisfies Assumption 1 (3) e.g. if J is of the form

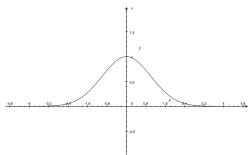
$$J(x) = \int_{\mathbb{R}^d} \cos(\langle y, x \rangle) \sigma(dy), \quad x \in \mathbb{R}^d,$$

for some **symmetric** probability measure σ on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d)) \longrightarrow$ **Bochner's theorem**.

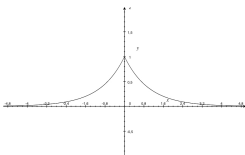
Examples $d = 1$ (characteristic functions)

In this case, J is a real-valued *characteristic function* of a symmetric probability [distribution](#).

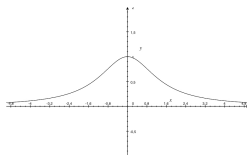
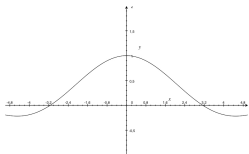
Gaussian



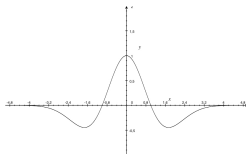
Cauchy



Laplace

Uniform (on $[-1, 1]$)

Maxwell–Boltzmann (“Mexican hat” wavelet)



The stochastic PDE

Let $\{W_t\}_{t \geq 0}$ be a cylindrical Wiener process with values in $H = L^2(\mathcal{B})$ on a filtered probability space $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$, $B \in L(H)$.

$$dU_t = [-\alpha U_t + KF(U_t)] dt + \varepsilon B dW_t, \quad U_0 = u_0 \in H, \quad t \in [0, T]. \quad (*)$$

Fact ([Da Prato, Zabczyk, *Cambridge Univ. Press* (1992)], see also [Kuehn, Riedler, *J. Math. Neuroscience* (2014)])

Let $B \in L_2(H)$. Then there exists a unique mild solution to (*) with $U \in C([0, T]; H)$, \mathbb{P} -a.s. having the form

$$U_t = e^{-\alpha t} u_0 + \int_0^t e^{-\alpha(t-s)} KF(U_s) ds + \varepsilon \int_0^t e^{-\alpha(t-s)} B dW_s \quad \text{in } H.$$

Section 2

A gradient flow formulation

Gradient flows

In fact even for $\varepsilon = 0$, it was not known, whether one can find a **gradient structure** to rewrite the PDE as

$$\partial_t u = -\nabla_{\mathcal{X}} \mathcal{F}(u), \quad u(\cdot, t) = u(t) \in \mathcal{X},$$

where \mathcal{X} is a suitable function space — Hilbert, Banach, or metric space (see e.g. [Ambrosio, Gigli, Savaré, *Birkhäuser* (2006)]) — and where

$$\mathcal{F} : \mathcal{X} \rightarrow \mathbb{R}$$

is a functional, which has often the natural interpretation of an **energy**, entropy or some other physical notion.

It was already seen in [Kuehn, Riedler, *J. Math. Neuroscience* (2014)] that the naïve guess for \mathcal{F} in $\mathcal{X} := L^2(\mathcal{B})$ fails to produce the desired formulation.

- └ A gradient flow formulation
- └ Change of ambient space

Change of ambient space

Recall: K is **trace-class**, **nonnegative definite**, **self-adjoint**. Hence:

- The spectrum $\sigma(K)$ is **discrete** with zero being its only accumulation point.
- There exists an orthonormal basis $\{e_j\}$ of eigenvectors in $L^2(\mathcal{B})$ such that the eigenvalues $\lambda_j \in \sigma(K) \setminus \{0\}$ satisfy w.l.o.g.

$$\lim_{i \rightarrow \infty} \lambda_i = 0.$$

We have the orthogonal decomposition

$$H = \text{Ker}(K) \oplus S$$

where $S := \text{Ker}(K)^\perp = \overline{\text{span}\{e_j\}_{j \in \mathbb{N}}}$.

On S becomes a separable Hilbert space (denoted by H_{-1}) with norm

$$\|u\|_{-1} := \|K^{-\frac{1}{2}}u\|_H \quad u \in S,$$

where $K^{-\frac{1}{2}}$ is the *Moore-Penrose pseudo-inverse* of $K^{\frac{1}{2}}$.

- └ A gradient flow formulation
- └ Change of ambient space

Gradients

Let $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ be any **primitive function** of f . Set

$$\Phi(u) := \int_{\mathcal{B}} \varphi(u(x)) \, dx \quad u \in H,$$

and let

$$\Psi(v) := \frac{\alpha}{2} \|v\|_{-1}^2, \quad u \in S.$$

Lemma

Φ is well-defined, finite for all $u \in H$ and continuous in H . Furthermore, we have that

$$D\Phi(u)h = (F(u), h)_H, \quad u, h \in H,$$

where $D\Phi(u)h$ denotes the **Gâteaux-directional derivative** of Φ in u in direction h .

- └ A gradient flow formulation
- └ Change of ambient space

Gradients

Furthermore, set $\Theta(u) := \Psi(u) - \Phi|_S(u)$, $u \in S$.

Lemma

For $u, h \in H_{-1}$, we have that

$$D\Theta(u)h = \alpha(u, h)_{-1} - (KF(u), h)_{-1},$$

where $D\Theta(u)h$ denotes the Gâteaux-directional derivative of Φ in u in direction h .

Compare also with the ideas of [Ren, Röckner, Wang, *J. Differential Equations* (2007)] and [Röckner, Wang, *J. Differential Equations* (2008)] \rightarrow generalized stochastic porous media equation.

However, in our situation, F is **not** assumed monotone.

- └ A gradient flow formulation
 - └ Change of ambient space

Inhibition and excitation

Remark

In the case that K is **nonpositive definite**, we can redefine H_{-1} by replacing K by $-K$ in the definition. Now, by changing the sign for Θ above, we obtain a gradient by a similar procedure. We can interpret the case of nonnegative definite symmetric kernels as domination by *excitation*, while the case of nonpositive definite kernels corresponds to domination of the *inhibition* effects.

- └ A gradient flow formulation
 - └ Change of ambient space

Gradient flow formulation

Let $\{W_t\}_{t \geq 0}$ be as above. Let $B \in L(H, H_{-1})$. Consider the **gradient flow** SPDE

$$dV_t = -D\Theta(V_t) dt + \varepsilon B dW_t, \quad V_0 = v_0 \in H_{-1}.$$

We shall assume below that $B \in L_2(H, H_{-1})$. Under the assumption that B is diagonalized w.r.t. $\{e_i\}$ with eigenvalues $\{b_i\}$, i.e.

$$B e_i = b_i e_i, \quad i \in \mathbb{N},$$

it holds that

Lemma

$$\{b_i^2 \lambda_i^{-1}\} \in \ell^1 \iff B \in L_2(H, H_{-1}).$$

One possibility is to set $B := K$, which corresponds to the continuum limit of a neural Langevin equation, see [Bressloff, *J. Phys. A* (2012)].

Gradient flow formulation (invariant subspace)

Theorem (Kuehn, T. (2018+), invariance of the subspace H_{-1})

For $B \in L_2(H, H_{-1})$, we have that there exists a unique mild solution $\{V_t\}_{t \geq 0}$ in H_{-1} such that, in particular, for $v_0 \in H_{-1}$, we have that $V \in L^2([0, T]; H_{-1})$ \mathbb{P} -a.s. and

$$\mathbb{E} \left[\sup_{t \in [0, T]} \|V_t\|_{-1}^2 \right] \leq C \|u_0\|_{-1}^2 + \varepsilon^2 C,$$

In particular, the mild solution in H_{-1} *coincides* with the mild solution in H for initial data in H_{-1} .

In our work, we also study strong and weak solutions to the above SPDE in H_{-1} via:

- Transformation of the additive noise,
- Dissipativity of the drift.

Invariant measures

Let $\{W_t\}_{t \geq 0}$ be a cylindrical Wiener process with values in H . Consider solutions to the equation

$$dX_t^{z,\varepsilon} = (AX_t^{z,\varepsilon} + D\Phi(X_t^{z,\varepsilon})) dt + \varepsilon dW_t, \quad X_0^{z,\varepsilon} = z \in H_{-1},$$

with $(Au, \cdot)_{-1} := -\alpha(K^{-1}u, \cdot)_H$ (which is the generator of a C_0 -semigroup $\{S_t\}_{t \geq 0}$ on H_{-1} which is the restriction of a C_0 -semigroup $\{S_t^0\}_{t \geq 0}$ on H).

Recall that $D\Phi(u)h = (F(u), h)_H$, $u, h \in H$.

Remark

We may w.l.o.g. assume that $t \mapsto \int_0^t S_{t-s}^0 dW_s \in C([0, T]; H_{-1})$ \mathbb{P} -a.s. as the semigroup $\{S_t^0\}_{t \geq 0}$ is *analytic*.

Invariant measures (existence)

Define the *transition semigroup*

$$P_t^\varepsilon G(z) := \mathbb{E} [G(X_t^{z,\varepsilon})] \quad t \geq 0, z \in H_{-1},$$

where $G : H_{-1} \rightarrow \mathbb{R}$ is bounded and measurable.

Theorem (by applying results from [Zabczyk, *SPDEs and Appl. II* (1989), Da Prato, Zabczyk, *Cambridge Univ. Press* (1992)])

Assume that $t \mapsto \int_0^t S_{t-s}^0 dW_s \in C([0, T]; H_{-1})$ \mathbb{P} -a.s. Then $\{P_t^\varepsilon\}_{t \geq 0}$ is **strongly Markovian** and **symmetric** with respect to its invariant measure, which **exists** and takes the following form

$$\mu_\varepsilon(dz) := \frac{1}{Z_\varepsilon} \exp [2\varepsilon^{-2}\Phi(z)] \gamma_\varepsilon(dz),$$

where $Z_\varepsilon := \int_{H_{-1}} \exp [2\varepsilon^{-2}\Phi(z)] \gamma_\varepsilon(dz)$ and $\gamma_\varepsilon \sim N(0, \Gamma_\varepsilon)$, where $\Gamma_\varepsilon := 2\varepsilon^2\alpha^{-1}K$.

Invariant measures (uniqueness)

Theorem (Compare with [Maslowski, *Stoch. Systems and Optim.* (1989)])

Assume that $t \mapsto \int_0^t S_{t-s}^0 dW_s \in C([0, T]; H_{-1})$ \mathbb{P} -a.s.. Then μ_ε is **strong Feller in the restricted sense** (asymptotic strong Feller) and thus **unique**, and the semigroup $\{P_t^\varepsilon\}_{t \geq 0}$ is **ergodic**.

Possible **applications**:

- Large deviation principle / small noise asymptotics,
- Kramers' law, (see e.g. [Berglund, *Markov Processes Related Fields* (2013)]),
- Kolmogorov operators / Fokker-Planck equations.

Final remarks

Possible [extensions](#):

- Situations where K and B do **not commute**,
- the situation of $\mathcal{B} = \mathbb{R}^d$,
- **multiplicative** noise,
- *indefinite* kernels K (however, with dominating positive or negative spectrum).



S. Amari.

Dynamics of pattern formation in lateral-inhibition type neural fields.

Biol. Cybernet., 27:77–87, 1977.



N. Berglund.

Kramers' law: validity, derivations and generalisations.

Markov Processes and Related Fields, 19(3):459–490, 2013.



P. C. Bressloff.

Spatiotemporal dynamics of continuum neural fields.

J. Phys. A, 45(033001):1–109, 2012.



O. Faugeras and J. Inglis.

Stochastic neural field equations: a rigorous footing.

J. Math. Biol., 71(2):259–300, 2015.



R. Jordan, D. Kinderlehrer, and F. Otto.

The variational formulation of the Fokker–Planck equation.

SIAM Journal on Mathematical Analysis, 29(1):1–17, 1998.



C. Kuehn and M. G. Riedler.

Large deviations for nonlocal stochastic neural fields.

J. Math. Neurosci., 4(1):1–33, 2014.



C. Kuehn and J. M. T.

A gradient flow formulation for the stochastic Amari neural field model.

Preprint, arXiv:1807.02575, submitted, 1–18, 2014.



B. Maslowski.

Strong Feller property for semilinear stochastic evolution equations and applications.

In *Stochastic Systems and Optimization*, pages 210–224. Springer, Berlin, Heidelberg, 1989.



H. Wilson and J. Cowan.

A mathematical theory of the functional dynamics of cortical and thalamic nervous tissue.

Biol. Cybern., 13(2):55–80, 1973.



J. Zabczyk.

Symmetric solutions of semilinear stochastic equations.

In *SPDEs and Applications II*, pages 237–256. Springer, Berlin, Heidelberg, 1989.

Thank you for your attention!