

A new take on ergodicity of the stochastic 2D Navier-Stokes equations

JONAS TÖLLE

(Aalto University, Finland)

joint work with GERARDO BARRERA (IST Lisboa, Portugal)

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Consider the stochastic incompressible 2D Navier-Stokes equations (NSE) with additive Wiener noise on a bounded domain $\mathcal{O} \subset \mathbb{R}^2$, viscosity $\nu > 0$,

$$dX_t = [\nu \Delta X_t + (X_t \cdot \nabla) X_t] dt + B dW_t, \quad t > 0,$$

$$\nabla \cdot X_t = 0, \quad t \geq 0,$$

$$X_0 = x \in L_{\text{sol}}^2(\mathcal{O}; \mathbb{R}^2) =: H,$$

with no-slip boundary condition $X_t = 0$ on $\partial \mathcal{O}$.

By the spectral Galerkin method, if $B \in \text{HS}(H)$ and if $\{W_t\}_{t \geq 0}$ is a cylindrical Wiener noise modelled on H , there exists a unique Markovian strong solution

$$X^x \in L_W^2([0, T] \times \Omega; H_{\text{sol},0}^1(\mathcal{O}; \mathbb{R}^2)).$$

The 2D NSE is an example of a *locally monotone drift SPDE*.

$$dX_t = A(X_t) dt + B dW_t, \quad t \geq 0.$$

Let $V \subset H \equiv H^* \subset V^*$ be a Gelfand triple.

V separable, reflexive Banach space, H separable Hilbert space.

$A: V \rightarrow V^*$ is called *monotone* if there exists $K \in \mathbb{R}$,

$$\langle A(u) - A(v), u - v \rangle \leq K \|u - v\|_H^2, \quad u, v \in V.$$

If $H = V = \mathbb{R}$, $f: \mathbb{R} \rightarrow \mathbb{R}$ is monotone **iff** $x \mapsto f(x) - Kx$ is non-increasing.

A is called *locally monotone* in V if there exists $\rho: V \rightarrow \mathbb{R}$, locally bounded and measurable, and $K \in \mathbb{R}$, such that

$$\langle A(u) - A(v), u - v \rangle \leq (K + \rho(u)) \|u - v\|_H^2, \quad u, v \in H.$$

Further examples of locally monotone drift SPDEs

- Stochastic power-law fluid equations
- Stochastic Allen-Cahn equation
- Stochastic Burgers equation

Non-monotone perturbations of monotone drift SPDEs

- Stochastic p -Laplace equation
- Stochastic porous medium-type equations

(not covered by our ergodicity result)

Further examples of locally monotone drift SPDEs

- Stochastic power-law fluid equations on $\mathcal{O} \subset \mathbb{R}^d$, $p \in (1, \infty)$,

$$dX_t = [\nabla \cdot S(e(X_t)) + (X_t \cdot \nabla) X_t] dt + B dW_t, \quad t > 0,$$

$$\nabla \cdot X_t = 0, \quad t \geq 0,$$

$$X_0 = x \in L^2_{\text{sol}}(\mathcal{O}; \mathbb{R}^d),$$

where

$$e(u)_{i,j} := \frac{1}{2}(\partial_i u_j + \partial_j u_i),$$

and

$$S(z) := 2\nu(1 + |z|)^{p-2}z.$$

Further examples of locally monotone drift SPDEs

- Stochastic power-law fluid equations on $\mathcal{O} \subset \mathbb{R}^d$, $p \in (1, \infty)$, $d = 2, 3$.

$$p > 2$$

dilatant, or shear-thickening
oobleck

(mixture of water and corn-starch)

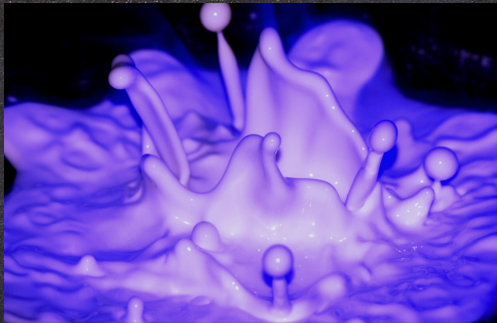


Image source: Rachel Grosskrueger (CU Boulder)

$$p < 2$$

pseudoplastic, or shear-thinning
hair gel, blood, whipped cream

(polymeric molecules)



Image source: Shutterstock

$$p = 2$$

Newtonian, Navier-Stokes equations
Examples: water, glycerol, ethanol

viscous stress \propto local strain rate



Image source: TROUT55/Getty Images

Further examples of locally monotone drift SPDEs

- Stochastic Allen-Cahn equation on $\mathcal{O} \subset \mathbb{R}^d$, $d = 1, 2, 3$.

$$dX_t = [\nu \Delta X_t + g(X_t)] dt + B dW_t, \quad t > 0,$$

$$X_0 = x \in L^2(\mathcal{O}).$$

Typically, $g(z) = z - z^3$.

- Stochastic Burgers equation on $\mathcal{O} \subset \mathbb{R}^d$, $d = 1, 2, 3$.

$$dX_t = [\nu \Delta X_t + \langle \mathbf{f}(X_t), \nabla X_t \rangle] dt + B dW_t, \quad t > 0,$$

$$X_0 = x \in L^2(\mathcal{O}).$$

1D stochastic Burgers, $d = 1$, $\mathbf{f}(z) = z$.

Existence and uniqueness of solutions to the examples for any finite time horizon $T > 0$ have been discussed in Liu, Röckner [LR10].

What about $T \rightarrow \infty$?

Replacing the noise $B dW$ by a deterministic forcing $f \in L^2_{\text{sol}}$, the 2D NSE with no-slip boundary condition is known to have **exponential convergence** to the stationary solution [Tem01], when **the viscosity is large enough** relative to constants depending only on the **domain**, the **first eigenvalue** of the Stokes operator, and the L^2_{sol} -norm of the **deterministic forcing** f .

Without forcing, the solution has **exponential decay** to zero.

What about the stochastic case?

Set $P_t F(x) := \mathbb{E}[F(X_t^x)]$, $t \geq 0$, $F \in \mathcal{B}_b(H)$, $x \in H$ and define P_t^* by duality

$$\langle P_t^* \mu, F \rangle = \langle P_t F, \mu \rangle, \quad t \geq 0, \mu \in \mathcal{M}_1(H), F \in C_b(H).$$

Definition 1. A probability measure $\mu \in \mathcal{M}_1(H)$ is said to be invariant for $\{P_t\}$ if $P_t^* \mu = \mu$ for every $t \geq 0$.

$\{P_t\}_{t \geq 0}$ is called Feller if $P_t(C_b(H)) \subset C_b(H)$ for every $t \geq 0$.

$\{P_t\}$ is called weak* mean ergodic if for some invariant measure μ ,

$$\frac{1}{T} \int_0^T P_t^* \nu dt \rightharpoonup \mu, \quad \text{as } T \rightarrow \infty$$

for every $\nu \in \mathcal{M}_1(H)$ which is equivalent to the uniqueness of μ .

Proposition 2. (Krylov-Bogoliubov).

If for a Feller semigroup $\{P_t\}$ and some $x \in H$, $t_n \nearrow \infty$, $\mu \in \mathcal{M}_1(H)$,

$$\frac{1}{t_n} \int_0^{t_n} \text{Law}(X_s^x) ds \rightharpoonup \mu \quad \text{as } n \rightarrow \infty$$

then μ is an invariant measure for $\{P_t\}$.

Remark 3. This method can be used to prove that the stochastic 2D NSE with additive Gaussian forcing admits an invariant measure by standard a priori estimates.

Definition 4. A Feller semigroup $\{P_t\}$ is said to have the strong Feller property if

$$P_t(\mathcal{B}_b(H)) \subset C_b(H) \quad \text{for every } t \geq 0.$$

A Feller semigroup $\{P_t\}$ is said to be *irreducible* if for every $t > 0$ and for every $x \in H$ and for every non-empty open set $O \subset H$,

$$P_t \mathbb{1}_O(x) > 0.$$

Theorem 5. If $\{P_t\}$ is strong Feller and irreducible, it admits a unique invariant measure μ such that for every $x \in H$

$$\|P_t^* \delta_x - \mu\|_{\text{TV}} \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

- In 1995, [Flandoli, Maslowski] proved the strong Feller property and irreducibility of the stochastic 2D NSE with non-degenerate Gaussian noise.
- In 2001–2002, the (exponential) ergodicity of the stochastic 2D NSE with either non-degenerate forcing or large viscosity ν was proved by Bricmont, Kupiainen, and Lefevere [BKL02]; E, Mattingly, and Sinai [EMS01]; Kuksin and Shirikyan [KS01]; Mattingly [Mat02]; ...
- In 2002, the general well-posedness theory for the stochastic 2D NSE was discussed by Menaldi and Sritharan [MS02].
- In 2006, Hairer and Mattingly [HM06] provided a minimal non-degeneracy condition of the noise for the asymptotic strong Feller property and weak irreducibility.
- **And many others ...**

Recently, there has been a lot of progress for multiplicative noise, Lévy noise, pure jump noise, and coupling techniques.

Hairer and Mattingly [HM06], [HM08] introduced the *asymptotic strong Feller property*, which admits the following **sufficient condition**.

Proposition 6. *Let $t_n \nearrow \infty$ and $\delta_n \searrow 0$, and $C: [0, \infty) \rightarrow \mathbb{R}$ nondecreasing. Then, $\{P_t\}$ is asymptotically strong Feller if for all $\varphi \in \text{Lip}_b(H)$,*

$$|\nabla P_{t_n} \varphi(x)| \leq C(\|x\|)(\|\varphi\|_\infty + \delta_n \|\nabla \varphi\|_\infty) \quad x \in H, n \in \mathbb{N}.$$

Definition 7. $\{P_t\}$ is called *weakly irreducible* if for every $x, y \in H$ there exists $z \in H$ such that for any $z \in O \subset H$ open, there exists $s, t > 0$ with

$$P_s \mathbb{1}_O(x) > 0 \quad \text{and} \quad P_t \mathbb{1}_O(y) > 0.$$

Theorem 8. *Weak irreducibility + Asymptotic strong Feller \Rightarrow Unique ergodicity.*

For the stochastic 2D NSE on the torus $\mathbb{T}^2 = [-\pi, \pi]^2$ in vorticity formulation

$$dv_t = [\nu \Delta v_t + u_t \cdot \nabla v_t] dt + \tilde{B} dW_t$$

where $v = \partial_2 u^1 - \partial_1 u^2$ is the vorticity, and u the velocity (which can be recovered by the Biot-Savart formula), one considers additive noise of the form

$\tilde{B} dW_t = \sum_{\mathbf{k}} \tilde{B} h_{\mathbf{k}} d\beta_t^{\mathbf{k}}$, where $\{\beta_t^{\mathbf{k}}\}_{t \geq 0}$, $\mathbf{k} \in \mathbb{Z}^2 \setminus \{(0, 0)\}$ are i.i.d. standard Brownian motions in \mathbb{R} , and $\{h_{\mathbf{k}}\}$ is the standard orthonormal basis (ONB) for $L^2(\mathbb{T}^2)$

$$h_{\mathbf{k}}(\xi) = \begin{cases} \sin(\mathbf{k} \cdot \xi), & \mathbf{k} \in \mathbb{Z}_+^2 \\ \cos(\mathbf{k} \cdot \xi), & \mathbf{k} \in \mathbb{Z}_-^2 \end{cases}, \quad \xi \in \mathbb{T}^2.$$

Let \mathcal{Z}_0 be a finite dimensional subset of $\mathbb{Z}^2 \setminus \{(0, 0)\}$ with

$\tilde{B}h_{\mathbf{k}} = 0$ when $\mathbf{k} \notin \mathcal{Z}_0$ and $\tilde{B}h_{\mathbf{k}} \neq 0$ when $\mathbf{k} \in \mathcal{Z}_0$.

The main result of [HM06] is the following minimal non-degeneracy condition.

Theorem 9. *Assume that $\mathcal{Z}_0 \subset \mathbb{Z}^2 \setminus \{(0, 0)\}$ is symmetric and finite dimensional such that*

- i. There exist at least two elements in \mathcal{Z}_0 with different Euclidean norms.*
- ii. Integer linear combinations of \mathcal{Z}_0 generate \mathbb{Z}^2 .*

Then the stochastic 2D NSE in vorticity formulation admits a unique invariant measure.

Example 10. $\mathcal{Z}_0 = \{(1, 0), (-1, 0), (1, 1), (-1, -1)\}$.

Denote by P_n the Galerkin projection on the first n Fourier modes. If the noise coefficient B is *mildly degenerate*, that is, $B \in \text{HS}(H)$ and for every $\nu > 0$, there exists $N = N(\nu, \|B\|_{\text{HS}(H)})$ such that, if

$$\text{Rg}(B) \supset P_n(H),$$

for some $n \geq N$, then the stochastic 2D NSE admits a unique invariant measure, and the *Foias-Prodi estimate* holds in the stochastic case for some $C = C(x, y, B, \mathcal{O}, \nu) > 0$, and $\delta = \delta(B, \mathcal{O}, \nu) > 0$ such that

$$\mathbb{E}[\|X_t^x - X_t^y\|_H^2] \leq C e^{-\delta t}$$

see e.g. [GMR17]. Thus, we get exponential mixing. The estimates rely on the properties of the **exponential martingale**.

Definition 11. A Feller semigroup $\{P_t\}$ is said to satisfy the e -property if for every $\varphi \in \text{Lip}_b(H)$, for every $x \in H$, for every $\varepsilon > 0$, there exists $\delta > 0$ such that

$$|P_t\varphi(x) - P_t\varphi(y)| < \varepsilon$$

for every $t \geq 0$ and for every $y \in H$ with $\|x - y\| < \delta$.

This type of uniform equicontinuity for bounded Lipschitz functions could be viewed a **coupling condition at infinity**.

It has been conjectured by Szarek and Worm [SW12] that

“It seems that all known examples of Markov processes with the asymptotic strong Feller property satisfy the e -property as well.”

Jaroszewska constructed a counter-example in 2013 in an unpublished preprint.

Originally developed by Lasota and Szarek [LS06], the “lower bound technique” can be described as follows in the work of Komorowski, Peszat and Szarek [KPS10].

Theorem 12. *Assume that $\{P_t\}$ is Feller and has the e -property. Assume that there exists $z \in H$ such that for every bounded set $J \subset H$ and every $\delta > 0$*

$$\inf_{x \in J} \liminf_{T \rightarrow \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_{B(z, \delta)}(x) dt > 0.$$

Suppose further that for every $\varepsilon > 0$ and every $x \in H$ there exists a bounded Borel set $K \subset H$ such that

$$\liminf_{T \rightarrow \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_K(x) dt > 1 - \varepsilon.$$

Then there exists a unique invariant probability measure μ for $\{P_t\}$, and $\{P_t\}$ is weak mean ergodic.*

Consider

$$(1) \quad dX_t = A(X_t) dt + dL_t, \quad t > 0, \quad X_0 = x_0,$$

where the **additive Lévy noise** is given by the Itô increment of

$$L_t = BW_t + \int_{\{\|z\| \leq 1\}} G(z) \tilde{N}(\{t\}, dz)$$

where $\{BW_t\}$ is as before (i.e., $\{W_t\}$ is a **cylindrical Wiener process** on H and $B \in \text{HS}(H)$), and $\tilde{N}((0, t] \times U) = N((0, t] \times U) - t\pi(U)$ is an independent **compensated Poisson random measure** with σ -finite intensity measure π on $\mathcal{B}(Z)$, where Z is a Banach space, such that $\pi(\{\|z\| > 1\}) < \infty$ (large jumps).

Let $G: Z \rightarrow H$ be strongly measurable with $\int_{\{\|z\| \leq 1\}} \|G(z)\|_H^2 \pi(dz) < \infty$.

As we consider just small jumps, $\{L_t\}$ is a **martingale**.

The drift $A: V \rightarrow V^*$ is *hemicontinuous* (i.e., weakly continuous along rays) and for $\alpha \geq 2$, $\delta_1 > 0$, $u \in V$,

$$2\langle A(u), u \rangle \leq \delta_1 \|u\|_V^\alpha \quad (\text{coercivity})$$

and for $\delta_2 > 0$, $C_2 \geq 0$, $u, v \in V$,

$$2\langle A(u) - A(v), u - v \rangle \leq (-\delta_2 + \rho(u)) \|u - v\|_H^2, \quad (\text{local monotonicity})$$

where for $\beta \geq 0$

$$0 \leq \rho(u) \leq C_2 \|u\|_V^\alpha \|u\|_H^\beta \quad u \in V.$$

Moreover, for $K > 0$, $u \in V$,

$$\|A(u)\|_{V^*}^{\frac{\alpha}{\alpha-1}} \leq K(1 + \|u\|_V^\alpha)(1 + \|u\|_H^\beta) \quad (\text{boundedness}).$$

Liu and Röckner (for Wiener noise) [LR10] and Brzezniak, Liu, and Zhu (for Lévy noise) [BLZ14] proved the following.

Theorem 13. *Under the previous hypotheses, for every initial datum*

$$x_0 \in L^{\beta+2}(\Omega, \mathcal{F}_0, \mathbb{P}; H)$$

there exists a unique strong adapted càdlàg solution $\{X_t\}$ with

$$X \in L^\alpha([0, T]; V) \cap L^2([0, T]; H) \quad \mathbb{P}\text{-a.s.}$$

such that every progressively measurable V -valued version of X satisfies (1) \mathbb{P} -a.s.

Note that our assumptions are intentionally not the most general ones, and exclude e.g. the stochastic p -Laplace equation, $p \neq 2$, or time-dependent drift.

Assume also that there exist $\delta_4 > 0$ and $C_4 \in \mathbb{R}$ such that for all $u \in V$,

$$2\langle A(u), u \rangle \leq C_4 - \delta_4 \|A(u)\|_{V^*} \quad (\text{cone condition}).$$

Remark 14. This condition is satisfied for the 2D NSE and the power law fluid equations. Unfortunately, it is quite restrictive for *semilinear equations* with drift $A = A_0 + F$ because it forces the nonlinear perturbation F of the dissipative principal term A_0 to have at most quadratic growth.

For this reason, our result does not cover stochastic Allen-Cahn equations with cubic nonlinearity.

Assume that $\int_{\{\|z\|\leq 1\}} \|G(z)\|_H^{\beta+2} \pi(dz) < \infty$, and that $\{L_t\}$ has the cylindrical representation

$$L_t = \sum_{k=1}^{\infty} \sqrt{\lambda_k} e_k l_t^k, \quad t \geq 0,$$

where $e_k \in V$, $k \in \mathbb{N}$ form an ONB of H , $\{\lambda_k\} \in \ell^1$ and $\{l_t^k\}$ are i.i.d. symmetric Lévy processes in \mathbb{R} with finite second moments.

Moreover, assume that for some $\|e_k\|_V \leq \sqrt{\sigma_k}$ with $\{\lambda_k \sigma_k\} \in \ell^1$ it holds that

$$\left\| \sum_{k=1}^{\infty} \sqrt{\lambda_k} e_k l_t^k \right\|_V^2 \leq \sum_{k=1}^{\infty} \lambda_k \sigma_k |l_t^k|^2.$$

If V is a separable Hilbert space, it is sufficient to assume that $\{\|e_k\|_V^{-1} e_k\}$ is an ONB of V .

Remark 15. If $G \equiv 0$, and V is a separable Hilbert space, the previous assumptions are equivalent to assuming that $B \in \text{HS}(H, V)$.

The symmetry and additional regularity of the Lévy process is needed to prove the *small ball property* in V .

Theorem 16. (Barrera, T., arXiv:2412.01381) *Under the previous hypotheses, the semigroup associated to (1) is Markovian and Feller, and satisfies the e -property and is weak* mean ergodic. The unique invariant probability measure μ on $(H, \mathcal{B}(H))$ admits finite $(\alpha + \beta)$ -moments in H . If $\beta = 0$, μ admits α -moments in V .*

The existence and uniqueness of μ is proved by the e -property and the lower-bound technique.

Theorem 17. *Under the hypotheses on the noise, the stochastic 2D NSE with additive Lévy noise admits a unique invariant measure with finite fourth moments.*

In particular, we cover the case of $O = \mathbb{T}^2$ and e.g. $\mathcal{Z}_0 = \{(1, 1)\}$ (2 Fourier modes), $\mathcal{Z}_0 = \{(1, 0)\}$ (1 Fourier mode) or $\mathcal{Z}_0 = \emptyset$ (the deterministic case), etc.

We point out that ergodicity and exponential mixing of passive scalars advected the velocity of the stochastic 2D NSE for less than 4 modes has been proved recently by Kooperman and Rowan [CR24] for initial data in $H_{\text{sol},0}^5(\mathbb{T}^2, \mathbb{R}^2)$.

Our result is true for all $\nu > 0$ and for initial data in $L_{\text{sol}}^2(\mathcal{O}, \mathbb{R}^2)$, however, we do not obtain a convergence rate. We get weak convergence of the time-averages of the law. Mixing for all $\nu > 0$ and degenerate noise is an open problem.

Here, $\rho(u) = \frac{64}{\nu^3} \|u\|_{L_{\text{sol}}^4}^4$, $\delta_2 = \nu c_0^2$, where c_0 is the inverse Poincaré constant of \mathcal{O} .

We also get ergodicity for the shear-thickening stochastic incompressible power law fluid equations with additive Lévy noise (the “oobleck case”).

Theorem 18. *Under the hypotheses on the noise, the stochastic power law fluid equation for $p \geq \frac{2+d}{2} \vee 2$ with additive Lévy noise admits a unique invariant measure with finite $\frac{2p}{2p-d}$ th moments.*

We first need to verify the e -property.

By a Galerkin approximation, Itô's lemma, and the Burkholder-Davis-Gundy inequality, we obtain the following a priori estimate for some constant $C > 0$, not depending on $T > 0$, and small enough $\gamma > 0$,

$$\begin{aligned} & \frac{1}{2} \mathbb{E} \left[\sup_{0 \leq t \leq T} \|X_t\|_H^{\beta+2} \right] + \delta_1 \frac{\beta+2}{4} \mathbb{E} \int_0^T e^{\gamma(t-T)} \|X_t\|_V^\alpha \|X_t\|_H^\beta dt \\ & \leq \mathbb{E} [\|x_0\|^{\beta+2} e^{-\gamma T}] + \frac{C}{\gamma} (1 - e^{-\gamma T}) \leq \mathbb{E} [\|x_0\|^{\beta+2}] + \frac{C}{\gamma}. \end{aligned}$$

For the 2D NSE, these types of estimates are well-known. In particular, applied for $\beta = 0$, we obtain the existence of at least one invariant measure by the Krylov-Bogoliubov theorem.

Recall:

Definition 19. A Feller semigroup $\{P_t\}$ is said to satisfy the ϵ -property if for every $\varphi \in \text{Lip}_b(H)$, for every $x \in H$, for every $\epsilon > 0$, there exists $\delta > 0$ such that

$$|P_t\varphi(x) - P_t\varphi(y)| < \epsilon$$

for every $t \geq 0$ and for every $y \in H$ with $\|x - y\| < \delta$.

Naïve proof.

$$|P_t\varphi(x) - P_t\varphi(y)| \leq \|\varphi\|_{\text{Lip}}^2 \mathbb{E}[\|X_t^x - X_t^y\|_H^2]$$

Note that if A is monotone, we get that

$$\mathbb{E}[\|X_t^x - X_t^y\|_H^2] = \|x - y\|_H^2 + 2\mathbb{E} \int_0^t \langle A(X_s^x) - A(X_s^y), X_s^x - X_s^y \rangle ds \leq \|x - y\|_H^2.$$

Note that because we have additive noise, for $0 < \gamma < \delta_2$, by local monotonicity,

$$\begin{aligned} & \|X_T^x - X_T^y\|_H^2 \\ &= \|x - y\|_H^2 e^{-\gamma T} + C_2 \int_0^T e^{\gamma(t-T)} \|X_t^x - X_t^y\|_H^2 ((\gamma - \delta_2) + \|X_t^x\|_V^\alpha \|X_t^x\|_H^\beta) dt \end{aligned}$$

Hence by the Gronwall lemma,

$$\begin{aligned} & \mathbb{E} \|X_T^x - X_T^y\|_H^2 + (\delta_2 - \gamma) \mathbb{E} \int_0^T e^{\gamma(t-T)} \|X_t^x - X_t^y\|_H^2 dt \\ & \leq \|x - y\|_H^2 \mathbb{E} \left[\exp \left(C_2 \int_0^T e^{\gamma(t-T)} \|X_t^x\|_V^\alpha \|X_t^x\|_H^\beta dt \right) \right] \end{aligned}$$

However, we do not have any control over the mean exponential.

Theorem 20. Let $s \geq 0$, let τ be a stopping time with values in $[s, \infty)$. Let $X, Y, f: [s, \tau) \times \Omega \rightarrow [0, \infty)$ be progressively measurable processes such that a.s. X has increasing and continuous paths, a.s. $Y \in L^1_{\text{loc}}([s, \tau))$, and a.s. $f \in L^1(s, \tau)$. Suppose that there exist constants $\eta \geq 0$ and $C \geq 1$ such that for all stopping times $s \leq \lambda \leq \Lambda \leq \tau$

$$\mathbb{E}[X(\Lambda)] + \mathbb{E} \int_{\lambda}^{\Lambda} Y(t) dt \leq C(\mathbb{E}[X(\lambda)] + \eta) + \mathbb{E} \left[(X(\Lambda) + \eta) \int_{\lambda}^{\Lambda} f(t) dt \right],$$

Then $X(\tau) + \int_s^{\tau} Y(t) dt$ is finite a.s. and for every $\varepsilon > 0, R > 0$,

$$\mathbb{P} \left(X(\tau) + \int_s^{\tau} Y(t) dt \geq \varepsilon \right) \leq \frac{4C}{\varepsilon} e^{4CR} (\mathbb{E}[X(0)] + \eta) + \mathbb{P} \left(\int_s^{\tau} f(t) dt \geq R \right).$$

Note. This enables us to dispense with *exponential martingales*.

Recall for $0 < \gamma < \delta_2$,

$$\begin{aligned} & \sup_{0 \leq t \leq T} \|X_t^x - X_t^y\|_H^2 \\ & \leq \|x - y\|_H^2 + C_2 \sup_{0 \leq t \leq T} \|X_t^x - X_t^y\|_H^2 \int_0^T e^{\gamma(t-T)} \|X_t^x\|_V^\alpha \|X_t^x\|_H^\beta dt. \end{aligned}$$

Now, by the stochastic Gronwall lemma [AV24], and the Markov inequality,

$$\begin{aligned} & \mathbb{P} \left(\sup_{0 \leq t \leq T} \|X_t^x - X_t^y\|_H^2 + (\delta_2 - \gamma) \int_0^T \|X_t^x - X_t^y\|_H^2 dt \geq \frac{\varepsilon^2}{9 \|\varphi\|_{\text{Lip}}} \right) \\ & \leq \frac{36}{\varepsilon^2} \|\varphi\|_{\text{Lip}}^2 e^{4R} \|x - y\|_H^2 + \frac{1}{R} \mathbb{E} \left[C_2 \int_0^T e^{\gamma(t-T)} \|X_t^x\|_V^\alpha \|X_t^x\|_H^\beta dt \right]. \end{aligned}$$

Recall the a priori estimate

$$\delta_1 \frac{\beta + 2}{4} \mathbb{E} \int_0^T e^{\gamma(t-T)} \|X_t^x\|_V^\alpha \|X_t^x\|_H^\beta dt \leq \|x\|^{\beta+2} + \frac{C}{\gamma}.$$

Hence, for fixed x and for any $T \geq 0$, by choosing suitable $R > 0$ and $\delta > 0$, recalling that $\|x - y\|_H \leq \delta$,

$$|P_t \varphi(x) - P_t \varphi(y)| \leq \frac{\varepsilon}{3} + 2\|\varphi\|_\infty \mathbb{P} \left(\sup_{0 \leq t \leq T} \|X_t^x - X_t^y\|_H^2 \geq \frac{\varepsilon^2}{9\|\varphi\|_{\text{Lip}}} \right)$$

$$\leq \frac{\varepsilon}{3} + 2\|\varphi\|_\infty \left(\frac{36}{\varepsilon^2} \|\varphi\|_{\text{Lip}}^2 e^{4R} \|x - y\|_H^2 + \frac{1}{R} \mathbb{E} \left[C_2 \int_0^T e^{\gamma(t-T)} \|X_t^x\|_V^\alpha \|X_t^x\|_H^\beta dt \right] \right)$$

$$\leq \frac{\varepsilon}{3} + 2\|\varphi\|_\infty \left(\frac{36}{\varepsilon^2} \|\varphi\|_{\text{Lip}}^2 e^{4R} \delta^2 + \frac{4C_2}{\delta_1(\beta+2)R} \left(\|x\|_H^{\beta+2} + \frac{C}{\gamma} \right) \right) \leq \varepsilon.$$

Consider the deterministic counterpart to (1),

$$du_t^x = A(u_t^x)dt, \quad t > 0, \quad u_0^x = x,$$

and note that by coercivity, for every $R > 0$,

$$\lim_{t \rightarrow \infty} \sup_{\|x\|_H^\alpha \leq R} \|u_t^x\|_H = 0.$$

Let us prove that for any $T > 0$, for any $\varepsilon > 0$, and any $K \subset H$ bounded, we have

$$\mathbb{P}(\|X_T^x - u_T^x\|_H^2 < \varepsilon) > 0,$$

uniformly for $x \in K$.

To prove this **stochastic stability** for finite times with positive probability, we use a pathwise argument to estimate $\|Y_t^x - u_t^x\|_H^2$, where $Y_t^x := X_t^x - L_t^x$ is the solution to the random PDE

$$dY_t = A(Y_t + L_t)dt, \quad t > 0, \quad Y_0 = x.$$

To control the error terms with positive probability, we need the *small ball property* of $\{L_t\}$ in V , that is,

$$\mathbb{P}\left(\sup_{0 \leq t \leq T} \|L_t\|_V < \delta\right) > 0.$$

which we can prove for symmetric Lévy processes in V . For the pathwise argument, we also need the non-standard assumption that there exist $\delta_4 > 0$ and $C_4 \in \mathbb{R}$ such that for all $u \in V$,

$$2\langle A(u), u \rangle \leq C_4 - \delta_4 \|A(u)\|_{V^*}.$$

We obtain

$$\begin{aligned} & \mathbb{P}\left(\sup_{0 \leq t \leq T} \|X_t^x - u_t^x\|_H^2 < \varepsilon\right) \\ & \geq \mathbb{P}\left(\sup_{0 \leq t \leq T} \|Y_t^x - u_t^x\|_H^2 < \frac{\varepsilon}{4}, \sup_{0 \leq t \leq T} \|L_t\|_H^2 < \frac{\varepsilon}{4}\right) > 0. \end{aligned}$$

However, in the estimates for $\sup_{0 \leq t \leq T} \|Y_t^x - u_t^x\|_H^2$, we in fact need the stronger requirement

$$\mathbb{P}\left(\sup_{0 \leq t \leq T} \|L_t\|_V^2 < \delta\right) > 0,$$

and an application of the stochastic Gronwall lemma.

Now, for every $\delta > 0$, and every $z \in K$, there exists $\gamma_1 > 0$, and $T_0 > 0$ such that

$$P_T \mathbb{1}_{B_\delta(0)}(z) = \mathbb{P}(\|X_{T_0}^z\|_H \leq \delta) \geq \mathbb{P}\left(\|X_{T_0}^z - u_{T_0}^z\|_H \leq \frac{\delta}{2}\right) \geq \gamma_1 > 0.$$

By a well-know trick used for instance by Es-Sarhir and von Renesse [EvR12], we may use the Markov property of the semigroup (shifting by T_0) to obtain

$$\liminf_{T \rightarrow \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_{B_\delta(0)}(x) dt \geq \liminf_{T \rightarrow \infty} \gamma_1 \frac{1}{T} \int_0^T P_t \mathbb{1}_K(x) dt > 0.$$

Here, we have also used that the coercivity implies for every $\varepsilon > 0$ and every bounded set J , there exists a bounded set K with

$$\inf_{x \in J} \liminf_{T \rightarrow \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_K(x) dt > 1 - \varepsilon.$$

Thus, the conditions of Komorowski, Peszat and Szarek [KPS10] can be verified. This proves our main result. The moment estimates follow from our a priori estimate and the fact that $V \subset H$ is a continuous linear embedding.

Theorem 21. *(Barrera, T., arXiv:2412.01381) Under the previous hypotheses, the semigroup associated to (1) is Markovian and Feller, and satisfies the e -property and is weak* mean ergodic. The unique invariant probability measure μ on $(H, \mathcal{B}(H))$ admits finite $(\alpha + \beta)$ -moments in H . If $\beta = 0$, μ admits α -moments in V .*

Remark 22.

- Due to our method, our proof is restricted to locally monotone equations, where ρ depends **only on one variable** and not on both (*fully locally monotone*).
- The V -**regularity** and **symmetry** of the noise are technical assumptions.

- We have proved the **ergodicity** of locally monotone drift SPDEs with Wiener noise plus independent symmetric Poisson noise with **spatial regularity** in the more regular space V without using *exponential martingales*.
- This extends the known results for **stochastic 2D NSE** for all $\nu > 0$ by a **new minimal condition** on the Fourier modes of the noise and by the **Poisson part**. Ergodicity for *mildly degenerate Lévy noise* is well-known.
- Other examples are the **stochastic power law fluid equations** for $p > 2$, the **stochastic heat equation**, and the **stochastic 1D Burgers equation**.
- Semilinear SPDEs like the **stochastic Allen-Cahn equation**, and *fully locally monotone* SPDEs like the **stochastic Cahn-Hilliard equation** are not covered by our results, nor is the **stochastic p -Laplace equation**.
- **Mixing** and quantification of mixing times remain an open question in this general situation.

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Thank you for your attention!