Ergodicity and mixing for locally monotone stochastic evolution equations

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Consider the stochastic incompressible 2D Navier-Stokes equations (NSE) with additive Wiener noise on a bounded domain $\mathcal{O} \subset \mathbb{R}^2$, viscosity $\nu > 0$,

$$dX_t = \left[\nu \Delta X_t + (X_t \cdot \nabla)X_t\right]dt + B dW_t, \quad t > 0,$$

$$\nabla \cdot X_t = 0, \quad t \ge 0,$$

$$X_0 = x \in L^2_{\text{sol}}(\mathcal{O}; \mathbb{R}^2) =: H,$$

with no-slip boundary condition $X_t = 0$ on $\partial \mathcal{O}$.

By the spectral Galerkin method, if $B \in \mathrm{HS}(U,H)$ and if $\{W_t\}_{t\geq 0}$ is a cylidrical Wiener noise modelled on a separable Hilbert space U, there exists a unique adapted Markovian strong solution

$$X^x \in L^2([0,T] \times \Omega; H^1_{sol,0}(\mathcal{O}; \mathbb{R}^2)).$$

Locally monotone drift SPDEs

The 2D NSE is an example of a locally monotone drift SPDE.

$$dX_t = A(X_t) dt + B dW_t, \quad t \ge 0.$$

Let $V \subset H \equiv H^* \subset V^*$ be a Gelfand triple.

V separable, reflexive Banach space, H separable Hilbert space.

 $A: V \to V^*$ is called *monotone* if there exists $K \in \mathbb{R}$,

$$\langle A(u) - A(v), u - v \rangle \le K \|u - v\|_H^2, \quad u, v \in V.$$

If $H = V = \mathbb{R}$, $f: \mathbb{R} \to \mathbb{R}$ is monotone **iff** $x \mapsto f(x) - Kx$ is non-increasing.

A is called *locally monotone* in V if there exists $\rho: V \to \mathbb{R}$, locally bounded and measurable, and $K \in \mathbb{R}$, such that

$$\langle A(u) - A(v), u - v \rangle \le (K + \rho(u)) \|u - v\|_H^2, \quad u, v \in H.$$

- Stochastic power-law fluid equations
- Stochastic Allen-Cahn equation
- Stochastic Burgers equation

Non-monotone perturbations of monotone drift SPDEs

- Stochastic p-Laplace equation + perturbation
- ullet Stochastic porous medium-type equations + perturbation

(not covered by our ergodicity result)

• Stochastic power-law fluid equations on $\mathcal{O}\subseteq\mathbb{R}^d$, $p\in(1,\infty)$,

$$dX_t = \left[\nabla \cdot S(\boldsymbol{e}(X_t)) + (X_t \cdot \nabla)X_t\right]dt + B dW_t, \quad t > 0,$$

$$\nabla \cdot X_t = 0, \quad t \ge 0,$$

$$X_0 = x \in L^2_{sol}(\mathcal{O}; \mathbb{R}^d),$$

where

$$e(u)_{i,j} := \frac{1}{2} (\partial_i u_j + \partial_j u_i),$$

and

$$S(z) := 2\nu (1+|z|)^{p-2}z.$$

• Stochastic power-law fluid equations on $\mathcal{O}\subseteq\mathbb{R}^d$, $p\in(1,\infty)$, d=2,3.

p > 2

dilatant, or shear-thickening oobleck

p < 2

pseudoplastic, or shear-thinning hair gel, blood, whipped cream

p=2

Newtonian, Navier-Stokes equations Examples: water, glycerol, ethanol

(mixture of water and corn-starch)

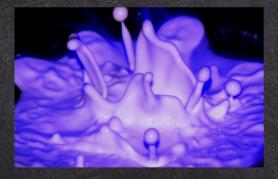


Image source: Rachel Grosskrueger (CU Boulder)

(polymeric molecules)



Image source: Shutterstock

viscous stress ∝ local strain rate



Image source: TROUT55/Getty Images

• Stochastic Allen-Cahn equation on $\mathcal{O}\subseteq\mathbb{R}^d$, d=1,2,3.

$$dX_t = \left[\nu \Delta X_t + g(X_t)\right] dt + B dW_t, \quad t > 0,$$

$$X_0 = x \in L^2(\mathcal{O}).$$

Typically, $g(z) = z - z^3$.

• Stochastic Burgers equation on $\mathcal{O} \subseteq \mathbb{R}^d$, d = 1, 2, 3.

$$dX_t = \left[\nu \Delta X_t + \langle \boldsymbol{f}(X_t), \nabla X_t \rangle\right] dt + B dW_t, \quad t > 0,$$

$$X_0 = x \in L^2(\mathcal{O}).$$

1D stochastic Burgers, d=1, f(z)=z.

Existence and uniqueness of solutions to the examples for any finite time horizon T>0 have been discussed in Liu, Röckner [LR10].

What about $T \rightarrow \infty$?

Replacing the noise $B\ dW$ by a deterministic forcing $f\in L^2_{\rm sol}$, the 2D NSE with no-slip boundary condition is known to have **exponential convergence** to the stationary solution [Tem01], when **the viscosity is large enough** relative to constants depending only on the **domain**, the **first eigenvalue** of the Stokes operator, and the $L^2_{\rm sol}$ -norm of the **deterministic forcing** f.

Without forcing, the solution has **exponential decay** to zero.

What about the stochastic case?

Set $P_tF(x) := \mathbb{E}[F(X_t^x)]$, $t \ge 0$, $F \in \mathcal{B}_b(H)$, $x \in H$ and define P_t^* by duality

$$\langle P_t^* \mu, F \rangle = \langle P_t F, \mu \rangle, \quad t \ge 0, \ \mu \in \mathcal{M}_1(H), \ F \in C_b(H).$$

Definition 1. A probability measure $\mu \in \mathcal{M}_1(H)$ is said to be invariant for $\{P_t\}$ if $P_t^*\mu = \mu$ for every $t \ge 0$.

 $\{P_t\}_{t\geq 0}$ is called Feller if $P_t(C_b(H))\subset C_b(H)$ for every $t\geq 0$.

 $\{P_t\}$ is called weak* mean ergodic if for some invariant measure μ ,

$$\frac{1}{T} \int_0^T P_t^* \nu dt \rightharpoonup \mu, \quad \text{as} \quad T \to \infty$$

for every $\nu \in \mathcal{M}_1(H)$ which is equivalent to the uniqueness of μ .

Proposition 2. (Krylov-Bogoliubov).

If for a Feller semigroup $\{P_t\}$ and some $x \in H$, $t_n \nearrow \infty$, $\mu \in \mathcal{M}_1(H)$,

$$\frac{1}{t_n} \int_0^{t_n} \text{Law}(X_s^x) ds \rightharpoonup \mu \quad \text{as} \quad n \to \infty$$

then μ is an invariant measure for $\{P_t\}$.

Remark 3. This method can be used to prove that the stochastic 2D NSE with additive Gaussian forcing admits an invariant measure by standard a priori estimates.

Definition 4. A Feller semigroup $\{P_t\}$ is said to have the strong Feller property if

$$P_t(\mathcal{B}_b(H)) \subset C_b(H)$$
 for every $t > 0$.

A Feller semigroup $\{P_t\}$ is said to be *irreducible* if for every t>0 and for every $x\in H$ and for every non-empty open set $O\subset H$,

$$P_t \mathbb{1}_O(x) > 0.$$

Theorem 5. If $\{P_t\}$ is strong Feller and irreducible, it admits a unique invariant measure μ such that for every $x \in H$

$$||P_t^*\delta_x - \mu||_{\text{TV}} \to 0 \quad \text{as} \quad t \to \infty.$$

Timeline (some highlights)

- In 1995, Flandoli and Maslowski [FM95] proved the strong Feller property and irreducibility of the stochastic 2D NSE with non-degenerate Gaussian noise.
- In 2001–2002, the (exponential) ergodicity of the stochastic 2D NSE with either non-degenerate forcing or large viscosity ν was proved by Bricmont, Kupiainen, and Lefevere [BKL02]; E, Mattingly, and Sinai [EMS01]; Kuksin and Shirikyan [KS01]; Mattingly [Mat02]; ...
- In 2002, the general well-posedness theory for the stochastic 2D NSE was discussed by Menaldi and Sritharan [MS02].
- In 2006, Hairer and Mattingly [HM06] provided a minimal non-degeneracy condition of the noise for the *asymptotic strong Feller property* and *weak irreducibility* with a minimal number of four forced modes.

And many others ...

Recently, there has been a lot of progess for multiplicative noise, Lévy noise, pure jump noise, and coupling techniques.

Denote by P_n the Galerkin projection on the first n Fourier modes. If the noise coefficient B is mildly degenerate, that is, $B \in \mathrm{HS}(H)$ and for every $\nu > 0$, there exists $N = N(\nu, \|B\|_{\mathrm{HS}(H)})$ such that, if

$$\operatorname{Rg}(B) \supset P_n(H),$$

for some $n \geq N$, then the stochastic 2D NSE admits a unique invariant measure, and the *Foias-Prodi estimate* holds in the stochastic case for some $C = C(x,y,B,\mathcal{O},\nu) > 0$, and $\delta = \delta(B,\mathcal{O},\nu) > 0$ such that

$$\mathbb{E}[\|X_t^x - X_t^y\|_H^2] \le Ce^{-\delta t}$$

see Glatt-Holtz, Mattingly, Richards [GMR17]. Thus, we get exponential mixing. The estimates rely on the properties of the **exponential martingale**.

Definition 6. A Feller semigroup $\{P_t\}$ is said to satisfy the e-property if for every $\varphi \in \operatorname{Lip}_b(H)$, for every $x \in H$, for every $\varepsilon > 0$, there exists $\delta > 0$ such that

$$|P_t\varphi(x) - P_t\varphi(y)| < \varepsilon$$

for every $t \ge 0$ and for every $y \in H$ with $||x - y|| < \delta$.

This type of uniform equicontinuity for bounded Lipschitz functions could be viewed a coupling condition at infinity.

It has been conjectured by Szarek and Worm [SW12] that

"It seems that all known examples of Markov processes with the asymptotic strong Feller property satisfy the e-property as well."

Jaroszewska constructed a counter-example in 2013 in an unpublished preprint.

The "lower bound technique"

Originally developed by Lasota and Szarek [LS06], the "lower bound technique" can be described as follows in the work of Komorowski, Peszat and Szarek [KPS10].

Theorem 7. Assume that $\{P_t\}$ is Feller and has the e-property. Assume that there exists $z \in H$ such that for every bounded set $J \subset H$ and every $\delta > 0$

$$\inf_{x \in J} \liminf_{T \to \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_{B(z,\delta)}(x) dt > 0.$$

Suppose further that for every $\varepsilon > 0$ and every $x \in H$ there exists a bounded Borel set $K \subset H$ such that

$$\liminf_{T \to \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_K(x) dt > 1 - \varepsilon.$$

Then there exists a unique invariant probability measure μ for $\{P_t\}$, and $\{P_t\}$ is weak* mean ergodic.

Generalized coupling techniques

The following conditions (more generally for couplings) have been inspired by Butkovsky, Kulik and Scheutzow [BKS20] (adapted to our situation). For a lower semi-continuous function $U: H \to [0, \infty)$ and a measurable function $S: H \to [0, \infty]$,

$$||X_t^x - X_t^y||_H^2 \le ||x - y||_H^2 \exp\left(-\zeta t + \kappa \int_0^t S(X_s^x) ds\right), \quad t \ge 0,$$

$$U(X_t^x) + \mu \int_0^t S(X_s^x) ds \le U(x) + bt + M_t, \quad t \ge 0,$$

where $\mu > 0$ and $b \ge 0$, such that

$$\zeta > \frac{\kappa b}{\mu},$$

and M is a continuous local martingale with $M_0 = 0$ and for $b_1, b_2 \ge 0$,

$$d\langle M \rangle_t \le b_1 S(X_t^x) dt + b_2 dt, \quad t \ge 0.$$

Consider

(1)
$$dX_t = A(X_t) dt + BdW_t$$
, $t > 0$, $X_0 = x_0$,

where $\{BW_t\}$ is as before, i.e., $\{W_t\}$ is a **cylindrical Wiener process** on a separable Hilbert space U and $B \in \mathrm{HS}(U,H)$.

The drift $A: V \to V^*$ is hemicontinuous (i.e., weakly continuous along rays) and for $\alpha \ge 2$, $\delta_1 > 0$, $u \in V$,

$$2\langle A(u), u \rangle \leq -\delta_1 ||u||_V^{\alpha}$$
 (coercivity)

and for $\delta_2 > 0$, $C_2 \ge 0$, $u, v \in V$,

$$2\langle A(u) - A(v), u - v \rangle \le (-\delta_2 + \rho(u)) \|u - v\|_H^2$$
, (local monotonicity)

where for $\beta \ge 0$

$$0 \le \rho(u) \le C_2 ||u||_V^{\alpha} ||u||_H^{\beta} \quad u \in V.$$

Moreover, for K > 0, $u \in V$,

$$||A(u)||_{V^*}^{\frac{\alpha}{\alpha-1}} \le K(1+||u||_V^{\alpha})(1+||u||_H^{\beta})$$
 (boundedness).

Existence and uniqueness of solutions

Liu and Röckner (for Wiener noise) [LR10] and Brzezniak, Liu, and Zhu (for Lévy noise) [BLZ14] proved the following.

Theorem 8. Under the previous hypotheses, for every initial datum

$$x_0 \in L^{\beta+2}(\Omega, \mathcal{F}_0, \mathbb{P}; H)$$

there exists a unique strong adapted càdlàg solution $\{X_t\}$ with

$$X \in L^{\alpha}([0,T];V) \cap L^{2}([0,T];H)$$
 \mathbb{P} -a.s.

such that every progressively measurable V-valued version of X satisfies (1) \mathbb{P} -a.s.

Note that our assumptions are intentionally not the most general ones, and exclude e.g. the stochastic p-Laplace equation, $p \neq 2$, or time-dependent drift.

Non-standard hypothesis on the drift

Assume also that there exist $\delta_4 > 0$ and $C_4 \in \mathbb{R}$ such that for all $u \in V$,

$$2\langle A(u), u \rangle \leq C_4 - \delta_4 ||A(u)||_{V^*}$$
 (cone condition).

Remark 9. This condition is satisfied for the 2D NSE and the power law fluid equations. Unfortunately, it is quite restrictive for *semilinear equations* with drift $A = A_0 + F$ because it forces the nonlinear perturbation F of the dissipative principal term A_0 to have **at most quadratic growth**.

For this reason, our result does not cover stochastic Allen-Cahn equations with cubic nonlinearity.

Quantitative conditions for ergodicity and mixing

Assume that the noise is spatially regular: $B \in HS(U, V)$ (if V is a Hilbert space, otherwise assume a small ball property in V).

To control the exponential martingale, we need to assume that

$$\alpha \ge 2, \quad 0 \le \beta \le \alpha - 2,$$

and a relation between $||B||_{\mathrm{HS}(U,H)}^2 \ge 0$, $\delta_1, \delta_2 > 0$, $C_2 \ge 0$, and $c_0 > 0$ such that

$$||v||_V \ge c_0 ||v||_H, \quad v \in V,$$

as follows: If $\beta = 0$, $\alpha = 2$, we assume that there exists $\gamma \in [0, \delta_2]$

$$||B||_{\mathrm{HS}(U,H)}^2 \le \frac{\delta_1}{C_2} (\delta_2 - \gamma) \wedge \frac{1}{4} \delta_1 c_0^2$$

If $\alpha > 2$, or $\beta > 0$, we assume an additional condition of similar type.

For the **2D NSE**, we have that $\alpha=2$, $\beta=0$, $\delta_1=2\nu$, $\delta_2=\nu c_0^2$, $C_2=\frac{4}{\nu}$,

see [BKS20]. Here, c_0 is the inverse of the Poincaré constant of the domain $\mathcal{O} \subset \mathbb{R}^2$. Note that in [BKS20], it is assumed also that there exists $n \in \mathbb{N}$ with

$$\operatorname{Rg}(B) \supset P_n(H),$$

which we do not have to assume here.

For the **1D Burgers equation**, we have that there exists $\varepsilon \in (0, 2\nu c_0^2)$, and $C = C(\varepsilon, c_0, \mathcal{O}) > 0$, such that:

$$\alpha = 2$$
, $\beta = 0$, $\delta_1 = 2\nu$, $\delta_2 = 2\nu c_0^2 - \varepsilon$, $C_2 = C$.

Certainly, the **stochastic heat equation** is also covered with:

$$\alpha = 2$$
, $\beta = 0$, $\delta_1 = 2\nu$, $\delta_2 = 2\nu c_0^2$, $C_2 = 0$.

Theorem 10. (Barrera, T., 2025+) Under the previous hypotheses, the semi-group associated to (1) is Markovian and Feller, and satisfies the e-property and is weak* mean ergodic. The unique invariant probability measure μ on $(H, \mathcal{B}(H))$ admits finite $(\alpha + \beta)$ -moments in H. If $\beta = 0$, μ admits α -moments in V.

The existence and uniqueness of μ is proved by the e-property and the lower-bound technique.

Let $\tau^x(\varepsilon) := \inf\{t \ge 0 : \mathcal{W}_2(\operatorname{Law}(X_t^x), \mu) \le \varepsilon\}$ be the **Markovian mixing time** with prescribed error $\varepsilon > 0$, here \mathcal{W}_2 denotes the Wasserstein-2-distance.

Theorem 11. (Barrera, T., 2025+) Under the previous hypotheses, if $\gamma > 0$, there exists a constant $K \ge 0$, such that we obtain the following upper bound:

$$\tau^{x}(\varepsilon) \leq \frac{2}{\gamma} \left[\frac{C_{2} ||x||_{H}^{\beta+2}}{4\delta_{1}(\beta+2)} + \log\left(||x||_{H} + \left(\frac{K}{2c_{0}^{\alpha}\delta_{1}(\beta+2)}\right)^{1/(\alpha+\beta)}\right) + \log\left(\frac{1}{\varepsilon}\right) \right].$$

Mixing time for stochastic 2D NSE

Theorem 12. (Barrera, T., 2025+) Assume that there exists $\gamma \in (0, \nu c_0^2]$, such that

$$||B||_{\mathrm{HS}(U,H)}^2 \le \frac{1}{8}\nu^2(\nu c_0^2 - \gamma) \wedge \frac{1}{2}\nu c_0^2,$$

then we obtain the following upper bound for the ε -mixing time

$$\tau^{x}(\varepsilon) \leq \frac{2}{\gamma} \left[\frac{2\|x\|_{H}^{2}}{\nu^{2}} + \log\left(\|x\|_{H} + \frac{\|B\|_{\mathrm{HS}(U,H)}}{\sqrt{\nu}c_{0}}\right) + \log\left(\frac{1}{\varepsilon}\right) \right]$$

for the stochastic 2D Navier-Stokes equations.

4 Sketch of the proof

We first need to verify the e-property.

By a Galerkin approximation and Itô's lemma, we obtain the following pathwise a priori esimate for some constant C>0, not depending on T>0,

$$||X_t^x||_H^{\beta+2} + \delta_1 \frac{\beta+2}{4} \int_0^T ||X_t||_V^{\alpha} ||X_t||_H^{\beta} dt$$

$$\leq ||x||^{\beta+2} + CT + M_T,$$

where $t \mapsto M_t$ is a local martingale with $M_0 = 0$. The absolutely continuous terms on the RHS have been compensated with the 2nd term on the LHS by our hypotheses and Young's inequality.

For the 2D NSE, these types of estimates are well-known. In particular, applied for $\beta = 0$, we obtain the existence of at least one invariant measure by the Krylov-Bogoliubov theorem.

Recall:

Definition 13. A Feller semigroup $\{P_t\}$ is said to satisfy the e-property if for every $\varphi \in \operatorname{Lip}_b(H)$, for every $x \in H$, for every $\varepsilon > 0$, there exists $\delta > 0$ such that

$$|P_t\varphi(x) - P_t\varphi(y)| < \varepsilon$$

for every $t \ge 0$ and for every $y \in H$ with $||x - y|| < \delta$.

Naïve proof.

$$|P_t\varphi(x) - P_t\varphi(y)| \le ||\varphi||_{\text{Lip}}^2 \mathbb{E}[||X_t^x - X_t^y||_H^2]$$

Note that if A is monotone, we get that

$$\mathbb{E}[\|X_t^x - X_t^y\|_H^2] = \|x - y\|_H^2 + 2\mathbb{E}\int_0^t \langle A(X_s^x) - A(X_s^y), X_s^x - X_s^y \rangle ds \le \|x - y\|_H^2.$$

Note that because we have additive noise, for $0 < \gamma < \delta_2$, by local monotonicity,

$$\frac{d}{dt}||X_t^x - X_t^y||_H^2$$

$$\leq ||X_t^x - X_t^y||_H^2 (-\delta_2 + C_2 ||X_t^x||_V^\alpha ||X_t^x||_H^\beta), \quad t > 0.$$

Hence by Gronwall's lemma,

$$|E||X_T^x - X_T^y||_H^2$$

$$\leq ||x - y||_H^2 \mathbb{E}\left[\exp\left(-\delta_2 T + C_2 \int_0^T ||X_t^x||_V^\alpha ||X_t^x||_H^\beta dt\right)\right], \quad T \geq 0.$$

We are left with controlling the exponential moments, which is not obvious.

The exponential martingale

By our assumption $\alpha \geq \beta - 2$, we can even obtain for another constant $\tilde{C} > 0$,

$$||X_t^x||_H^{\beta+2} + \delta_1 \frac{\beta+2}{4} \int_0^T ||X_t||_V^{\alpha} ||X_t||_H^{\beta} dt$$

$$\leq ||x||^{\beta+2} + \tilde{C}T + M_T - \frac{1}{2} \langle M \rangle_T.$$

Now,

$$\mathbb{E}\left[\exp\left(M_T - \frac{1}{2}\langle M \rangle_T\right)\right] = 1.$$

Hence, for the *e*-property, we just need

$$\delta_2 \ge \frac{4C_2}{\delta_1(\beta+2)}\tilde{C},$$

which follows from our hypotheses.

Stochastic stability

Consider the deterministic counterpart to (1),

$$du_t^x = A(u_t^x) dt, \quad t > 0, \quad u_0^x = x,$$

and note that by coercivity, for every R > 0,

$$\lim_{t\to\infty} \sup_{\|x\|_H\leq R} \|u_t^x\|_H = 0.$$

Let us prove that for any T > 0, for any $\varepsilon > 0$, and any $K \subset H$ bounded, we have

$$\mathbb{P}(\|X_T^x - u_T^x\|_H^2 < \varepsilon) > 0,$$

uniformly for $x \in K$.

To prove this **stochastic stability** for finite times with positive probability, we use a pathwise argument to estimate $||Y_t^x - u_t^x||_H^2$, where $Y_t^x := X_t^x - L_t^x$ is the solution to the random PDE

$$dY_t = A(Y_t + L_t)dt, \quad t > 0, \quad Y_0 = x.$$

To control the error terms with positive probability, we need the *small ball property* of $\{L_t\}$ in V, that is,

$$\mathbb{P}\left(\sup_{0 \le t \le T} ||L_t||_V < \delta\right) > 0.$$

which we can prove for symmetric Lévy processes in V. For the pathwise argument, we also need the non-standard assumption that there exist $\delta_4 > 0$ and $C_4 \in \mathbb{R}$ such that for all $u \in V$,

$$2\langle A(u), u \rangle \le C_4 - \delta_4 ||A(u)||_{V^*}.$$

We obtain

$$\mathbb{P}\left(\sup_{0 \le t \le T} \|X_t^x - u_t^x\|_H^2 < \varepsilon\right)$$

$$\ge \mathbb{P}\left(\sup_{0 < t < T} \|Y_t^x - u_t^x\|_H^2 < \frac{\varepsilon}{4}, \sup_{0 < t < T} \|L_t\|_H^2 < \frac{\varepsilon}{4}\right) > 0.$$

However, in the estimates for $\sup_{0 \le t \le T} \|Y^x_t - u^x_t\|_H^2$, we in fact need the stronger requirement

$$\mathbb{P}\left(\sup_{0 \le t \le T} ||L_t||_V^2 < \delta\right) > 0,$$

and an application of the stochastic Gronwall lemma by Sarah Geiss [Gei24] (see also von Renesse and Scheutzow [vRS10]).

Now, for every $\delta > 0$, and every $z \in K$, there exists $\gamma_1 > 0$, and $T_0 > 0$ such that

$$P_T \mathbb{1}_{B_{\delta}(0)}(z) = \mathbb{P}(\|X_{T_0}^z\|_H \le \delta) \ge \mathbb{P}\left(\|X_{T_0}^z - u_{T_0}^z\|_H \le \frac{\delta}{2}\right) \ge \gamma_1 > 0.$$

By a well-know trick used for instance by Es-Sarhir and von Renesse [EvR12], we may use the Markov property of the semigroup (shifting by T_0) to obtain

$$\liminf_{T \to \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_{B_{\delta}(0)}(x) dt \ge \liminf_{T \to \infty} \gamma_1 \frac{1}{T} \int_0^T P_t \mathbb{1}_K(x) dt > 0.$$

Here, we have also used that the coercivity implies for every $\varepsilon > 0$ and every bounded set J, there exists a bounded set K with

$$\inf_{x \in J} \liminf_{T \to \infty} \frac{1}{T} \int_0^T P_t \mathbb{1}_K(x) dt > 1 - \varepsilon.$$

Thus, the conditions of Komorowski, Peszat and Szarek [KPS10] can be verified.

This proves our main result. The moment estimates follow from our a priori estimate and the fact that $V \subset H$ is a continuous linear embedding.

Theorem 14. (Barrera, T.) Under the previous hypotheses, the semigroup associated to (1) is Markovian and Feller, and satisfies the e-property and is weak* mean ergodic. The unique invariant probability measure μ on $(H, \mathcal{B}(H))$ admits finite $(\alpha + \beta)$ -moments in H. If $\beta = 0$, μ admits α -moments in V.

Remark 15.

- Due to our method, our proof is restricted to locally monotone equations, where ρ depends **only on one variable** and not on both (*fully locally monotone*).
- ullet The V-regularity and symmetry of the noise are technical assumptions.

Wrap-up and open problems

- We have proved the **ergodicity** of locally monotone drift SPDEs with Wiener noise plus independent small-jump symmetric Poisson noise with **spatial regularity** in the more regular space V under quantitative conditions with **degenerate noise**. The embedding $V \subset H$ does not need to be compact.
- Further examples are the **stochastic power law fluid equations** for p>2, the **stochastic heat equation**, and the **stochastic 1D Burgers** equation.
- Semilinear SPDEs like the **stochastic Allen-Cahn equation**, and *fully locally monotone* SPDEs like the **stochastic Cahn-Hilliard equation** are not covered by our results, nor is the **stochastic** *p*-**Laplace equation**.

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Thank you for your attention!